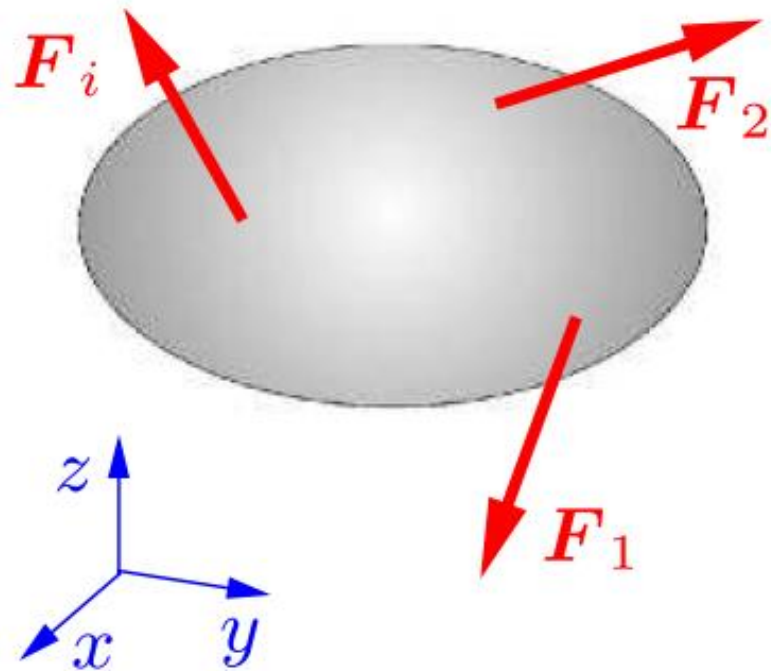


CHAPTER 3

EQUILIBRIUM in 3D

- We extend our principles and methods developed for *two-dimensional* equilibrium to the case of *three-dimensional* equilibrium.

$$\sum \vec{F} = 0 \quad , \quad \sum \vec{M} = 0$$

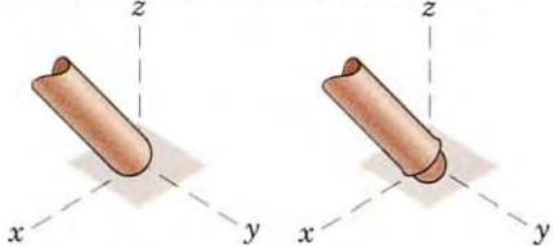
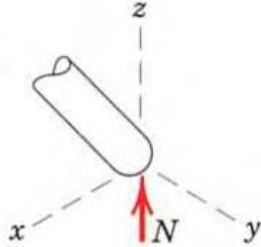
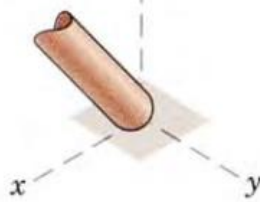
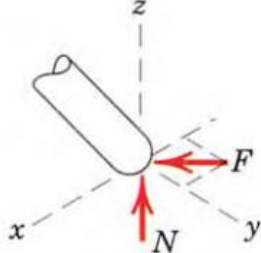
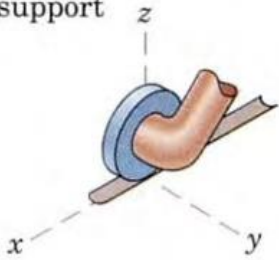
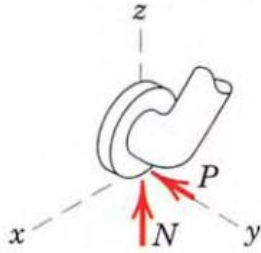


$$\sum \vec{F} = 0 \quad , \quad \sum \vec{M} = 0$$

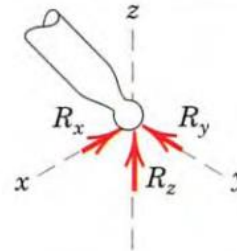
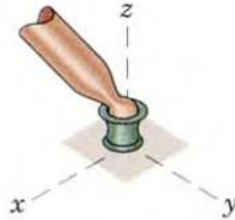
Free-Body Diagram

- For drawing free-body diagram of 3D problems, we use same steps with 2D problems.
- Step 1. *Decide* which *system* to isolate.
- Step 2. Next *isolate* the chosen *system* by drawing a *diagram* which represents its complete *external boundary*.
- Step 3. *Identify* all *forces* which act on the *isolated system* as applied by the removed contacting and attracting bodies.
- Step 4. *Show* the choice of *coordinate axes* directly on the diagram.

MODELING THE ACTION OF FORCES IN THREE-DIMENSIONAL ANALYSIS

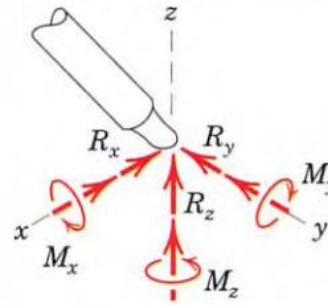
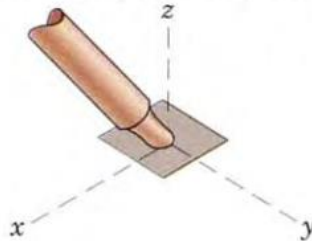
Type of Contact and Force Origin	Action on Body to Be Isolated
<p>1. Member in contact with smooth surface, or ball-supported member</p> 	 <p>Force must be normal to the surface and directed toward the member.</p>
<p>2. Member in contact with rough surface</p> 	 <p>The possibility exists for a force F tangent to the surface (friction force) to act on the member, as well as a normal force N.</p>
<p>3. Roller or wheel support with lateral constraint</p> 	 <p>A lateral force P exerted by the guide on the wheel can exist, in addition to the normal force N.</p>

4. Ball-and-socket joint



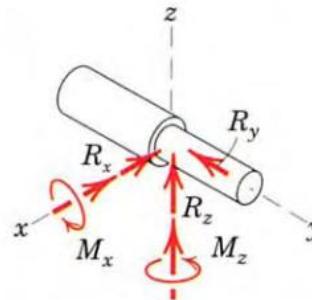
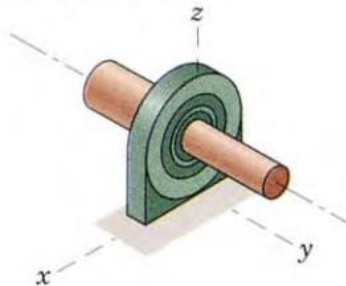
A ball-and-socket joint free to pivot about the center of the ball can support a force \mathbf{R} with all three components.

5. Fixed connection (embedded or welded)



In addition to three components of force, a fixed connection can support a couple \mathbf{M} represented by its three components.

6. Thrust-bearing support



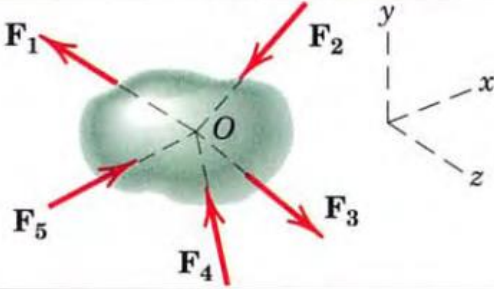
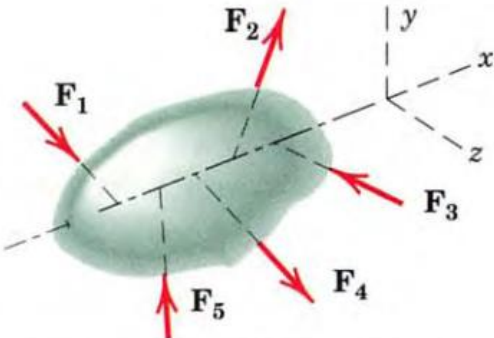
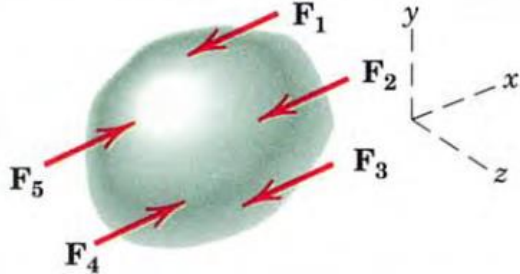
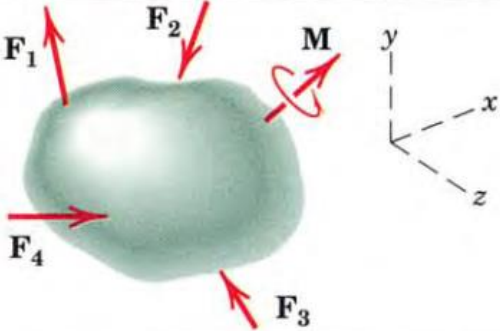
Thrust bearing is capable of supporting axial force R_y as well as radial forces R_x and R_z . Couples M_x and M_z must, in some cases, be assumed zero in order to provide statical determinacy.

Equilibrium Conditions

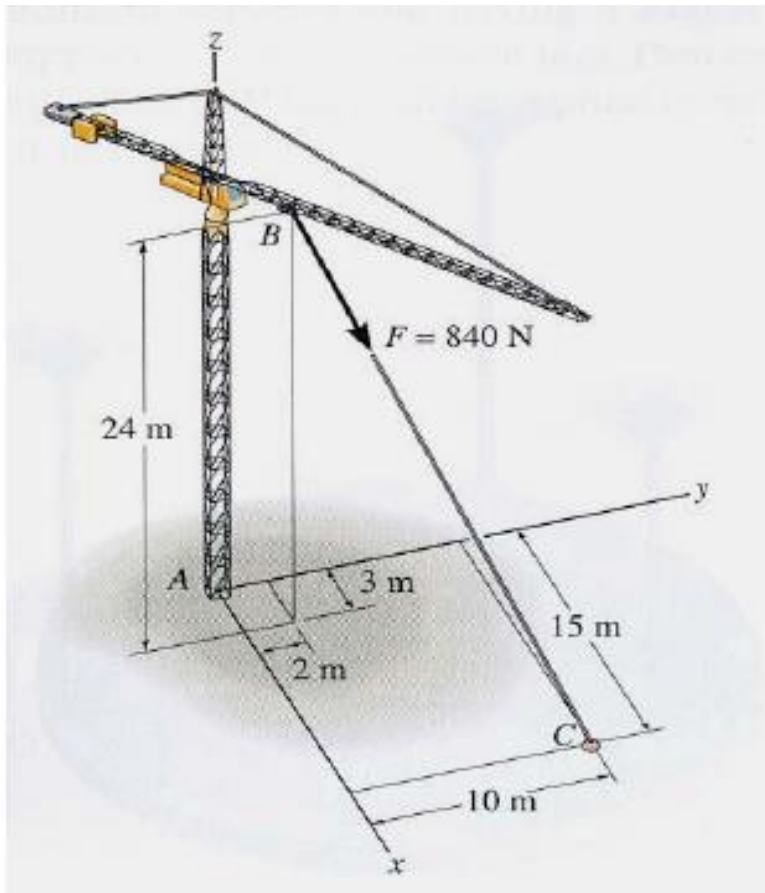
- All resultant *forces* and *moments* on the each *three axes* must be *zero*.

$$\sum F_x = 0 \ , \ \sum F_y = 0 \ , \ \sum F_z = 0$$

$$\sum M_x = 0 \ , \ \sum M_y = 0 \ , \ \sum M_z = 0$$

CATEGORIES OF EQUILIBRIUM IN THREE DIMENSIONS		
Force System	Free-Body Diagram	Independent Equations
1. Concurrent at a point		$\Sigma F_x = 0$ $\Sigma F_y = 0$ $\Sigma F_z = 0$
2. Concurrent with a line		$\Sigma F_x = 0$ $\Sigma F_y = 0$ $\Sigma F_z = 0$ $\Sigma M_y = 0$ $\Sigma M_z = 0$
3. Parallel		$\Sigma F_x = 0$ $\Sigma M_y = 0$ $\Sigma M_z = 0$
4. General		$\Sigma F_x = 0$ $\Sigma F_y = 0$ $\Sigma F_z = 0$ $\Sigma M_x = 0$ $\Sigma M_y = 0$ $\Sigma M_z = 0$

Example



Given: The cable of the tower crane is subjected to 840 N force. A fixed base at A supports the crane.

Find: Reactions at the fixed base A.

Solution

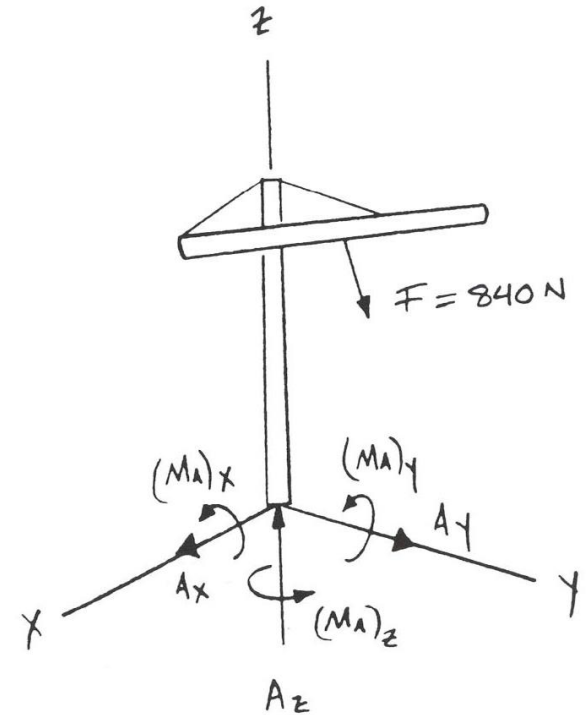
$$\mathbf{r}_{BC} = \{12 \mathbf{i} + 8 \mathbf{j} - 24 \mathbf{k}\} \text{ m}$$

$$\mathbf{F} = F [\mathbf{n}_{BC}] \text{ N}$$

$$= 840 [12 \mathbf{i} + 8 \mathbf{j} - 24 \mathbf{k}] / (12^2 + 8^2 + (-24^2))^{1/2}$$

$$= \{360 \mathbf{i} + 240 \mathbf{j} - 720 \mathbf{k}\} \text{ N}$$

$$\mathbf{F}_A = \{A_x \mathbf{i} + A_y \mathbf{j} + A_z \mathbf{k}\} \text{ N}$$



Solution

- From Equilibrium equation we get,

$$\mathbf{F} + \mathbf{F}_A = 0$$

$$\{(360 + A_x) \mathbf{i} + (240 + A_y) \mathbf{j} + (-720 + A_z) \mathbf{k}\} = 0$$

- Solving each component equation yields
- $A_x = -360 \text{ N}$,
- $A_y = -240 \text{ N}$, and $A_z = 720 \text{ N}$.

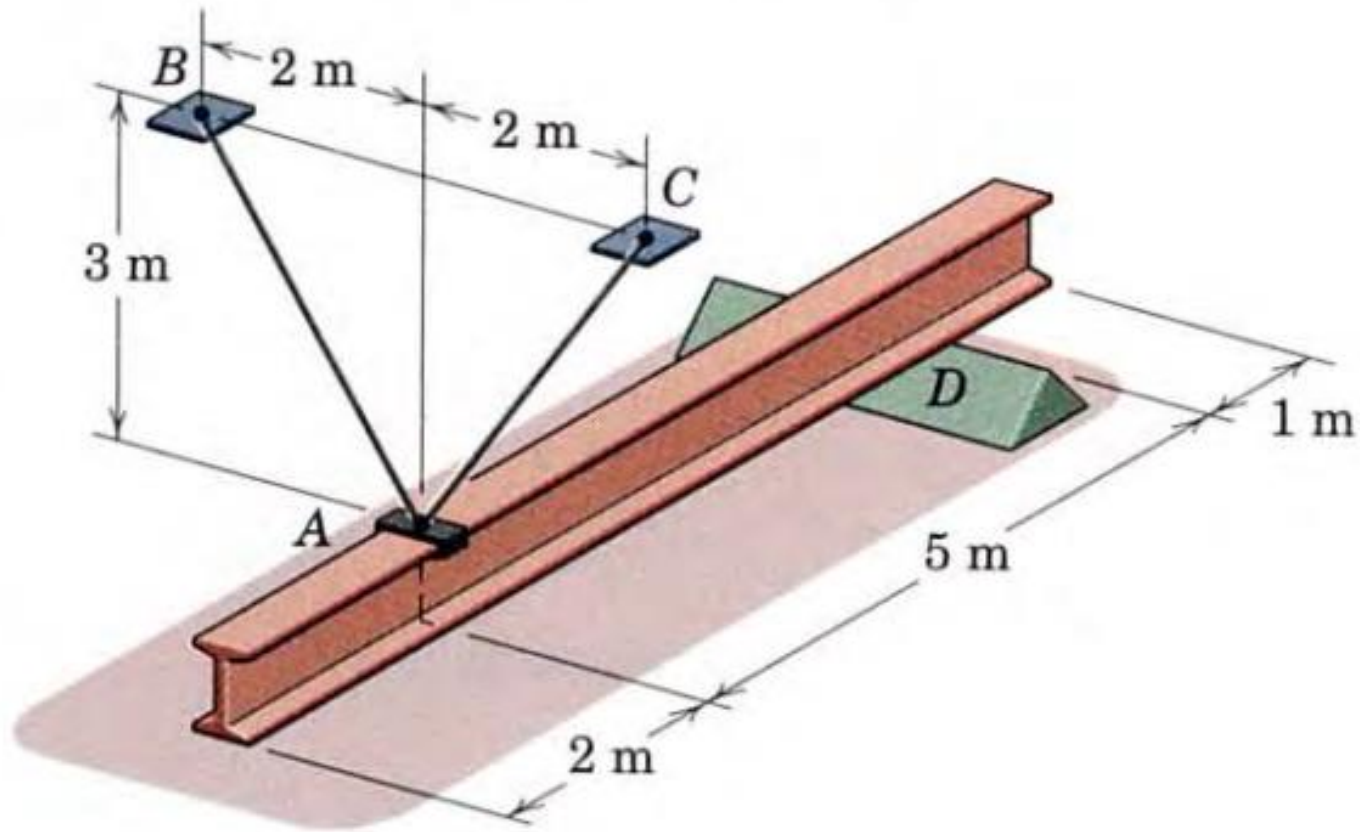
Sum the moments acting at point A.

$$\begin{aligned}\sum \mathbf{M} &= \mathbf{M}_A + \mathbf{r}_{AC} \times \mathbf{F} = 0 \\ &= M_{AX} \mathbf{i} + M_{AY} \mathbf{j} + M_{AZ} \mathbf{k} + \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 15 & 10 & 0 \\ 360 & 240 & -720 \end{vmatrix} = 0 \\ &= M_{AX} \mathbf{i} + M_{AY} \mathbf{j} + M_{AZ} \mathbf{k} - 7200 \mathbf{i} + 10800 \mathbf{j} = 0\end{aligned}$$

$$M_{AX} = 7200 \text{ N} \cdot \text{m}, M_{AY} = -10800 \text{ N} \cdot \text{m}, \text{ and } M_{AZ} = 0$$

Note: For simpler problems, one can directly use three scalar moment equations, $\sum M_X = \sum M_Y = \sum M_Z = 0$

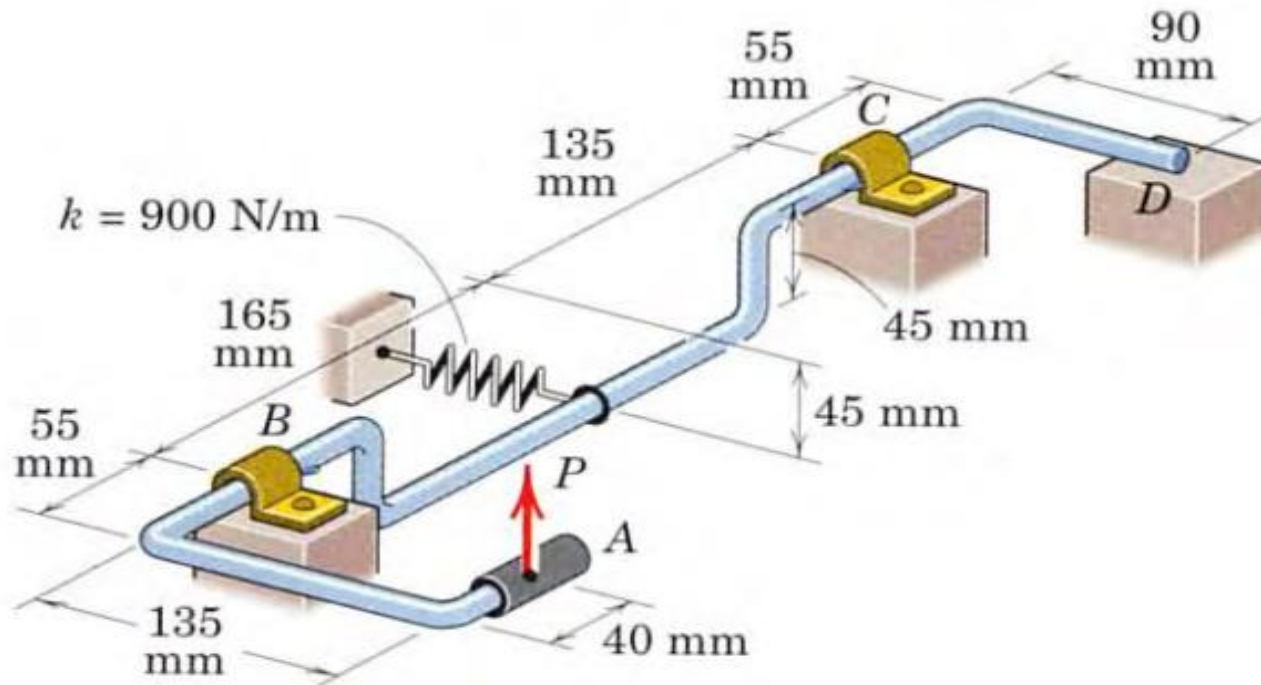
3/64 The uniform I-beam has a mass of 60 kg per meter of its length. Determine the tension in the two supporting cables and the reaction at D .



Problem 3/64

Results: $T=1698\text{N}$, $D=1884\text{N}$

3/80 The spring of modulus $k = 900 \text{ N/m}$ is stretched a distance $\delta = 60 \text{ mm}$ when the mechanism is in the position shown. Calculate the force P_{\min} required to initiate rotation about the hinge axis BC , and determine the corresponding magnitudes of the bearing forces which are perpendicular to BC . What is the normal reaction force at D if $P = P_{\min}/2$?



Problem 3/80

Results: $P_{\min} = 18 \text{ N}$, $B = 30.8$, $C = 29.7 \text{ N}$, $D = 13.5 \text{ N}$

example: A uniform pipe cover of radius 240 mm and mass 30 kg is held in a horizontal position by the cable CD . The bearings at A and B are self-aligning and bearing A resists thrust. Determine the cable tension and the reactions at A and B .

$$T = 343.4 \text{ N}$$

$$A_x = 49.1 \text{ N}$$

$$A_y = 73.6 \text{ N}$$

$$A_z = 98.1 \text{ N}$$

$$B_x = 245 \text{ N}$$

$$B_y = 73.5 \text{ N}$$

