CHAPTER 4

Frames and Machines

- Frames and machines are two types of structures which are often *composed* of *pin-connected* multiforce members, i.e., members that are subjected to *more* than *two forces*.
- Frames are used to support loads, whereas machines contains *moving parts* and are designed to *transmit* and *change* the effect of *forces*.

Analysis of Frames



- *Frames* and *machines* are structures with at least one *multiforce* member. Frames are designed to support loads and are usually stationary. Machines contain moving parts and are designed to transmit and modify forces.
- A free body diagram of the complete frame is used to determine the external forces acting on the frame.
- Internal forces are determined by dismembering the frame and creating free-body diagrams for each component.
- Forces on two force members have known lines of action but unknown magnitude and sense.
- Forces on multiforce members have unknown magnitude and line of action. They must be represented with two unknown components.
- Forces between connected components are equal, have the same line of action, and opposite sense.

Examples





















Sample Problem



Members ACE and BCD are connected by a pin at C and by the link DE. For the loading shown, determine the force in link *DE* and the components of the force exerted at C on member BCD.

SOLUTION:

- Create a free-body diagram for the complete frame and solve for the support reactions.
- Define a free-body diagram for member *BCD*. The force exerted by the link *DE* has a known line of action but unknown magnitude. It is determined by summing moments about C.
- With the force on the link *DE* known, the sum of forces in the x and y directions may be used to find the force components at *C*.
- With member *ACE* as a free-body, check the solution by summing moments about *A*.

Sample Problem



SOLUTION:

• Create a free-body diagram for the complete frame and solve for the support reactions.

$$\sum F_y = 0 = A_y - 480 \text{ N} \qquad A$$

$$\sum M_A = 0 = -(480 \text{ N})(100 \text{ mm}) + B(1)$$

$$B =$$

$$\sum F_x = 0 = B + A_x$$

$$A_{\chi}$$

Note: $\alpha = \tan^{-1} \frac{80}{150} = 28.07^{\circ}$

$V_{y} = 480 \text{ N}$

.60 mm) = 300 N

$= -300 \text{ N} \leftarrow$

Sample Problem

• Define a free-body diagram for member *BCD*. The force exerted by the link *DE* has a known line of action but unknown magnitude. It is determined by summing moments about *C*.



$$\sum M_C = 0 = (F_{DE} \sin \alpha)(250 \text{ mm}) + (300 \text{ N})(60 \text{ mm}) + (480 \text{ N})(100 \text{ mm})$$
$$F_{DE} = -561 \text{ N}$$

• Sum of forces in the *x* and *y* directions may be used to find the force components at *C*.

$$\sum F_x = 0 = C_x - F_{DE} \cos \alpha + 300 \text{ N}$$
$$0 = C_x - (-561 \text{ N}) \cos \alpha + 300 \text{ N}$$

$$\sum F_y = 0 = C_y - F_{DE} \sin \alpha - 480 \text{ N}$$
$$0 = C_y - (-561 \text{ N}) \sin \alpha - 480 \text{ N}$$

$$C_{x}$$

$$C_y$$

mm) $_{T} = 561 \text{ N} C$

= -795 N





 $\sum M_A = (F_{DE} \cos \alpha)(300 \text{ mm}) + (F_{DE} \sin \alpha)(100 \text{ mm}) - C_x(220 \text{ mm})$ $=(-561\cos\alpha)(300 \text{ mm})+(-561\sin\alpha)(100 \text{ mm})-(-795)(220 \text{ mm})=0$

(check S

Machines



- Machines are structures designed to transmit and modify forces. Their main purpose is to transform input forces into output forces.
- Given the magnitude of **P**, determine the I-Q \bullet magnitude of *Q*.
 - Create a free-body diagram of the complete machine, including the reaction that the wire exerts.
 - The machine is a nonrigid structure. Use one of the components as a free-body.
 - Taking moments about A,

$$\sum M_A = 0 = aP - bQ \qquad Q = \frac{a}{b}$$

P

























Solution procedures of Frames and Machines

- Firstly, In order to determine the *forces* acting at the *joints* and supports of a frame or machine, the structure must be *disassembled* and the *free-body diagrams* of its parts must be drawn.
- *isolate* each *part* by drawing its outlined shape. Then *show* all the *forces* and/or *couple moments* that act on the part.
- *Identify* all *two-force members* in the structure and represent their free-body diagram.
- Forces common to any two contacting members act with equal *magnitudes* but *opposite sense* on the respective members.

Example 2

4/81 A small bolt cutter operated by hand for cutting small bolts and rods is shown in the sketch. For a hand grip P = 150 N, determine the force Q developed by each jaw on the rod to be cut.



Ans. Q = 2.7 kN

Example 3

Determine the vertical clamping force at E in terms of the force P applied to the handle of the toggle clamp..



Example 4

The car hoist allowst the car to be driven onto the platform, after which the rear wheels are raised. If the loading from both rear wheels is 6 kN, determine the force in the hydraulic cylinder AB. Neglect the weight of the platform itself. Member BCD is a right-angle bell crank pinned to the ramp at C.





4/99 The toggle pliers are used for a variety of clamping purposes. For the handle position given by $\alpha = 10^{\circ}$ and for a handle grip P = 150 N, calculate the clamping force C produced. Note that pins A and D are symmetric about the horizontal centerline of the tool. Ans. C = 1368 N





F6–16. Determine the horizontal and vertical components of reaction at pin C. 400 N



F6-15. If a 100-N force is applied to the handles of the pliers, determine the clamping force exerted on the smooth pipe B and the magnitude of the resultant force at pin A.



