

AE 104

STATICS

CHAPTER 2

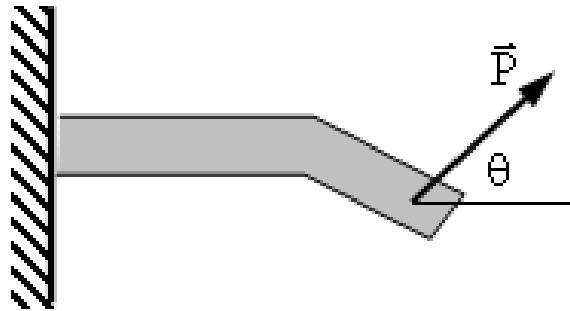
FORCE SYSTEMS

Introduction

- In this chapter, the *properties* and *effects* of various kinds of *forces* which *act on* engineering *structures* and *mechanisms* will be examined.

Force

- A *force* has been defined as the *action* of one body on another. We find that *force is a vector* quantity.

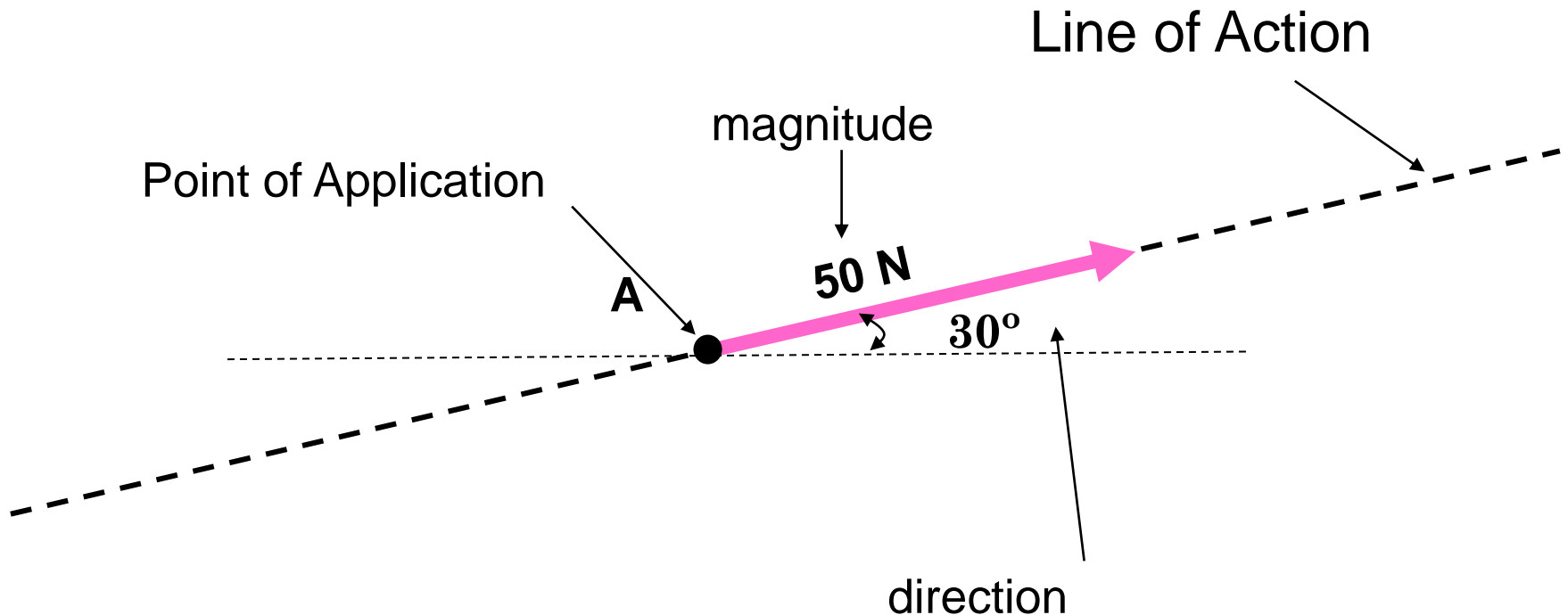


- The action of a force on a body can be separated into two effects,

External effect:

Internal effect:

- The complete *specification* of the action of a *force* must include its *magnitude*, *direction*, and *point of application*, in which case it is treated as a fixed vector.

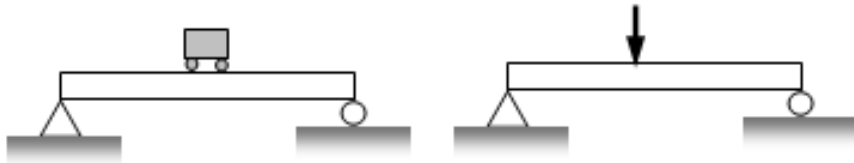


Since the vector has a well defined point of application, it is a fixed vector, therefore can not be moved without modifications

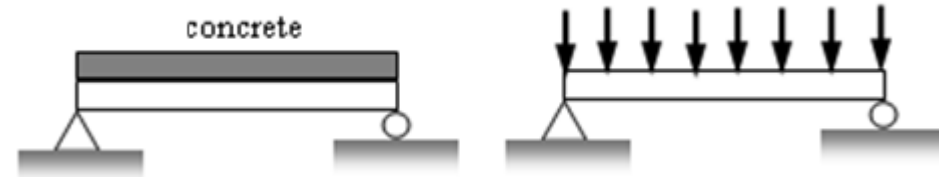
Classification of Forces

- Body force: Forces that are applied on whole body.
- Surface Force: Forces that are applied on surfaces of body.
- Concentrated (single) Force: When the dimensions of the area on which forces are applied are very small compared with the other dimensions of the body, The forces can be considered as concentrated at a point with negligible loss of accuracy.
- Distributed forces: Actually every contact force is applied over a finite area and is therefore a distributed force.

Single Load

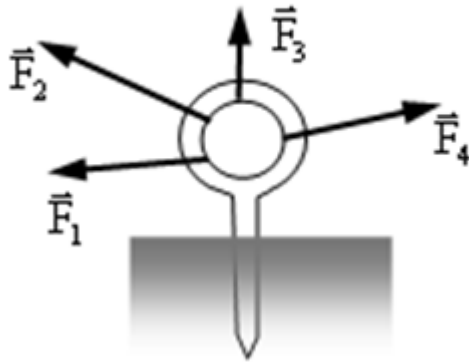


Distributed Load

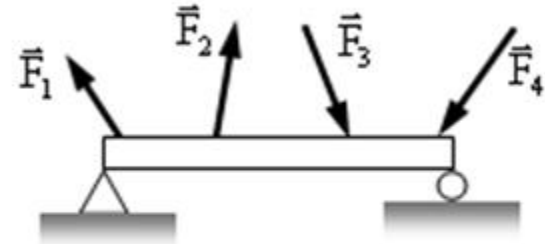


Forces due to application

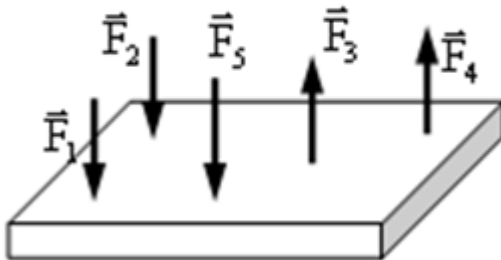
concurrent



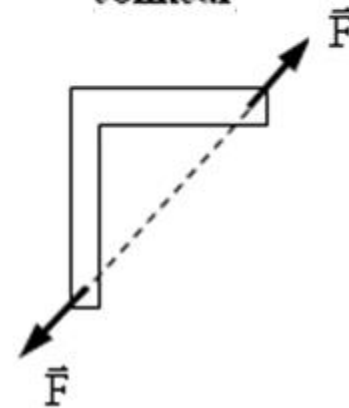
coplanar



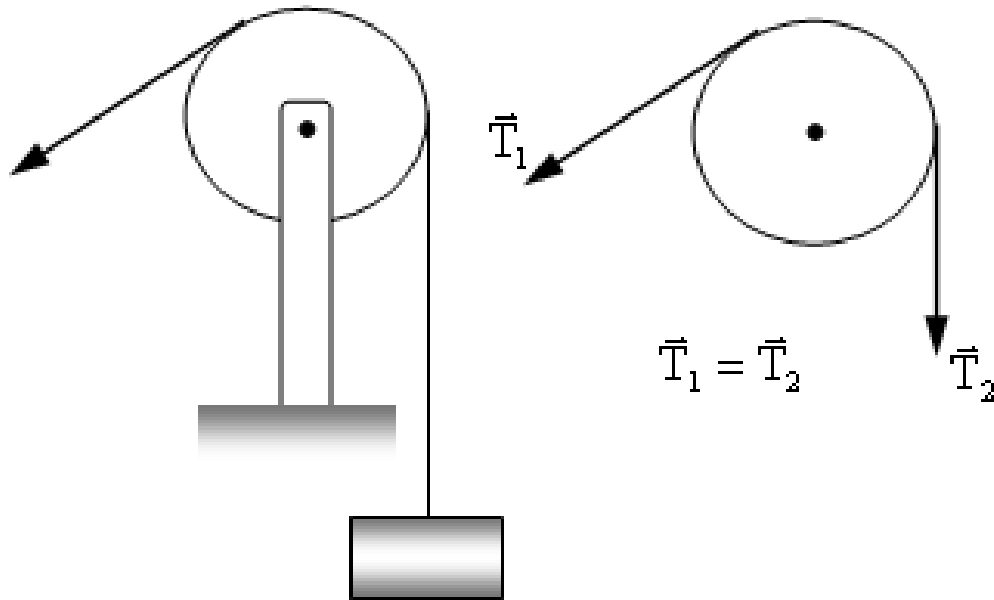
parallel



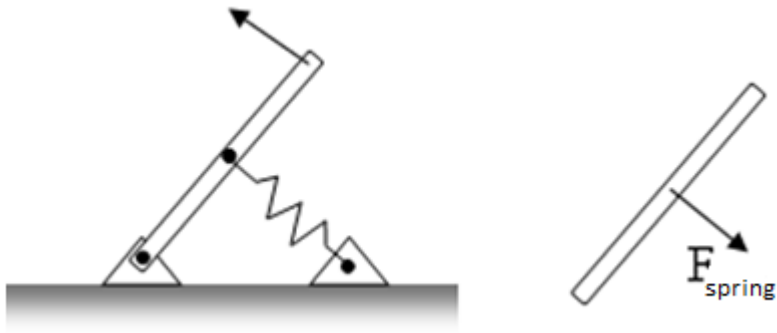
colinear



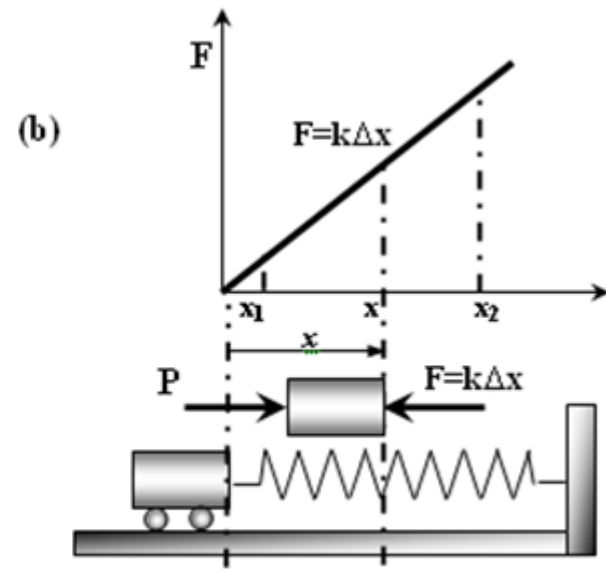
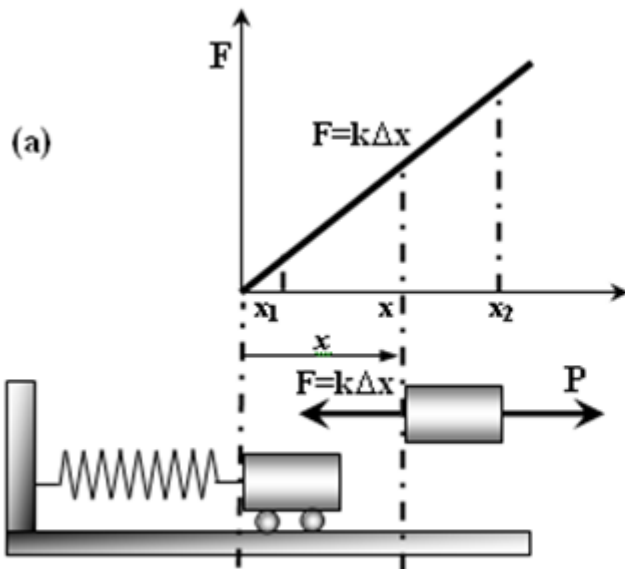
Forces on Pulley



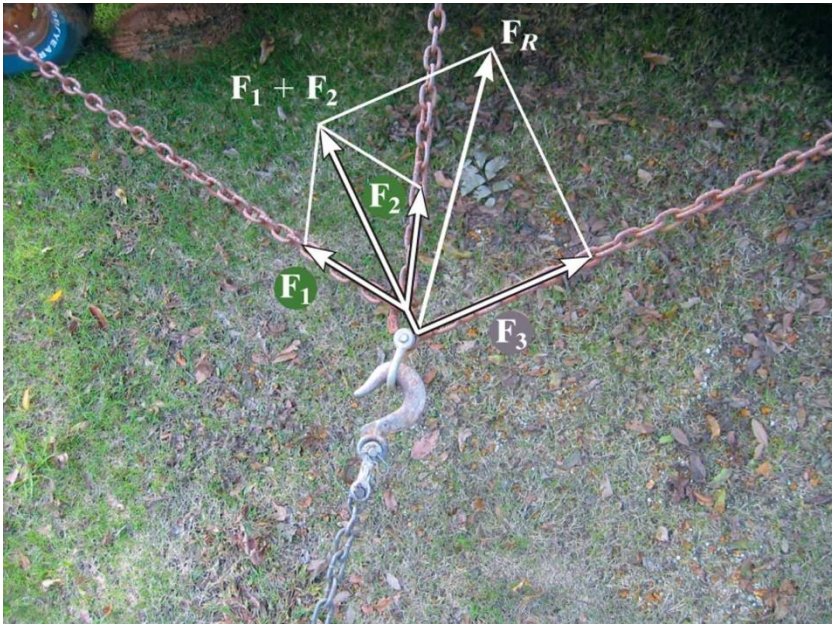
Forces on springs



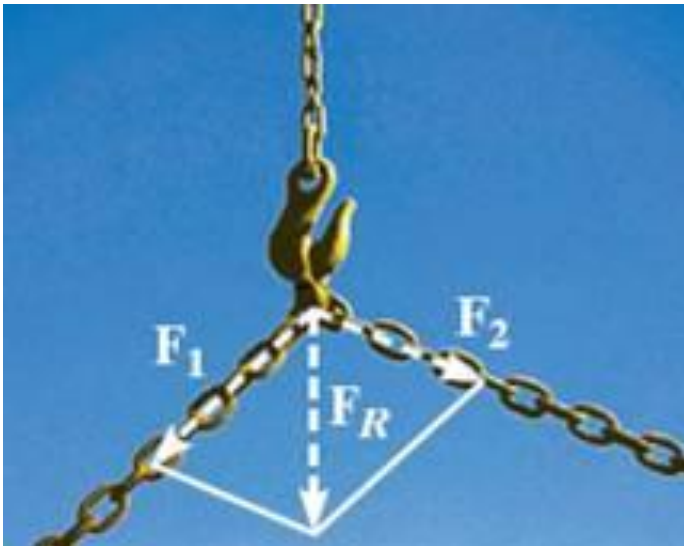
$$F_{\text{spring}} = k\Delta x$$



Addition of Forces in a Plane

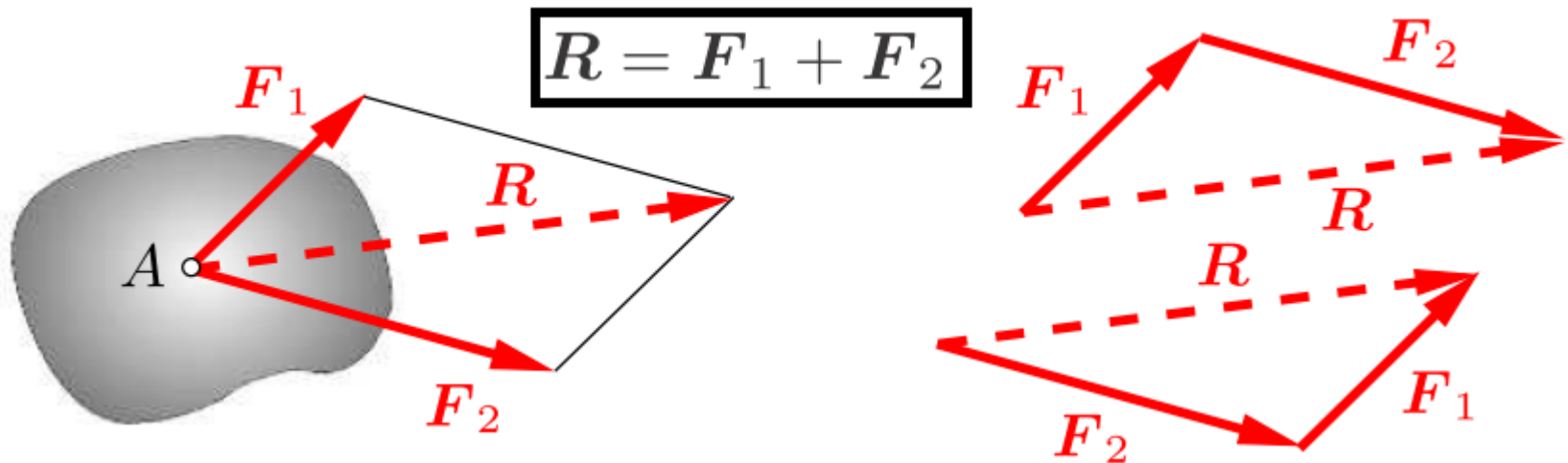


- There are some concurrent forces acting on the hook due to the chains.
- We need to decide if the hook will fail (bend or break)?
- To do this, we need to know the resultant force acting on the hook.



Addition of Forces in a Plane

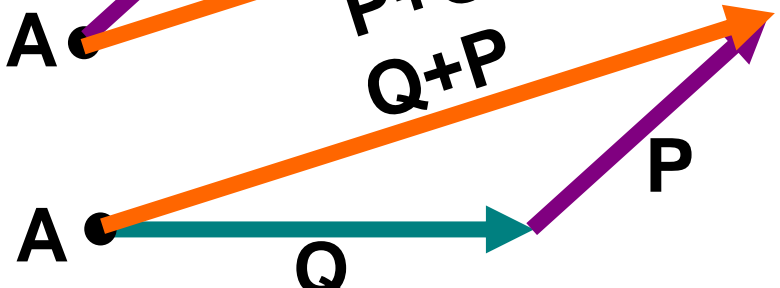
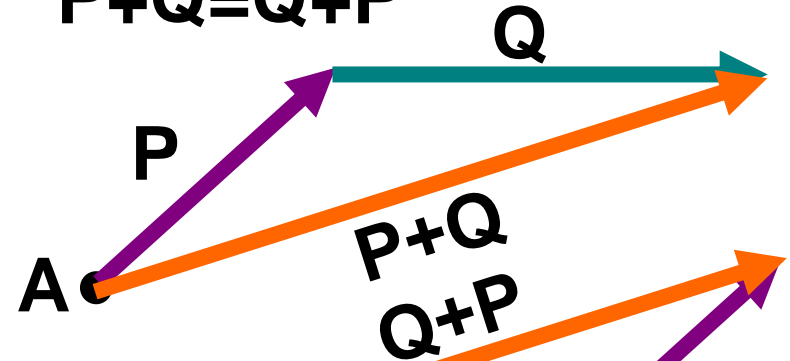
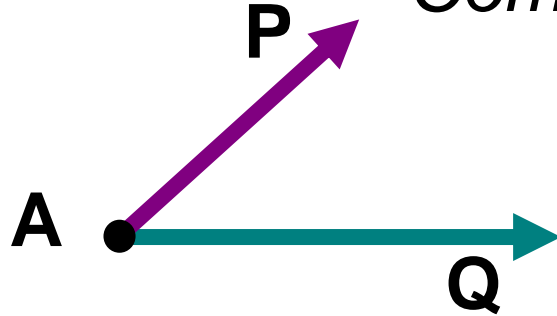
- The *effect* of two nonparallel *forces* F_1 and F_2 acting at a *point* A of a body is the same as the effect of the *single force* R acting at the same point and *obtained* as the *diagonal* of the *parallelogram* formed by F_1 and F_2 or it can be *obtained* by using *triangle method*.



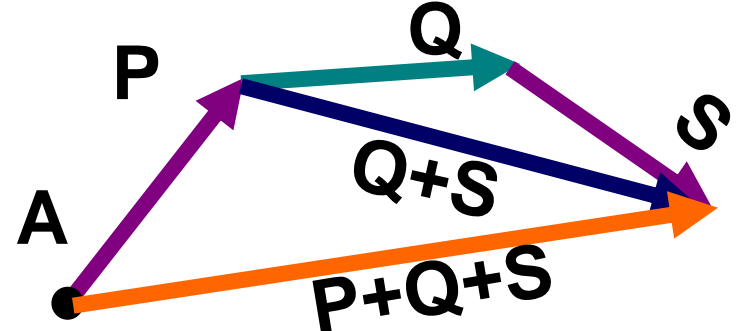
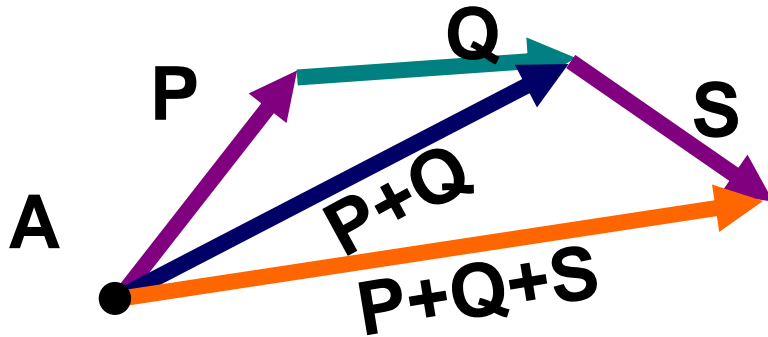
Properties of Vector Addition

Commutative

$$\mathbf{P} + \mathbf{Q} = \mathbf{Q} + \mathbf{P}$$

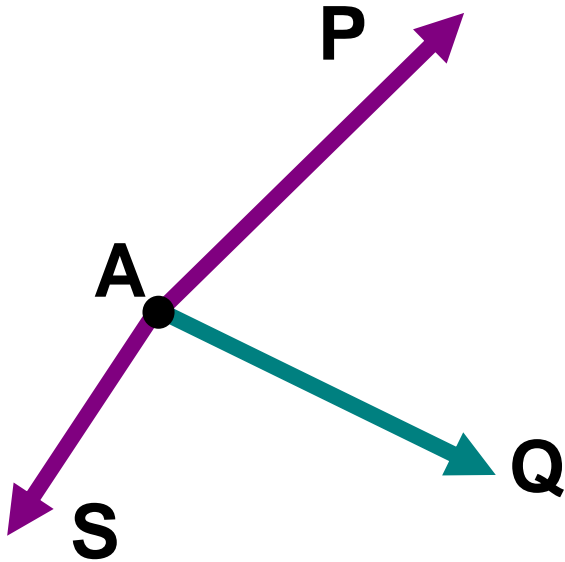


Associative

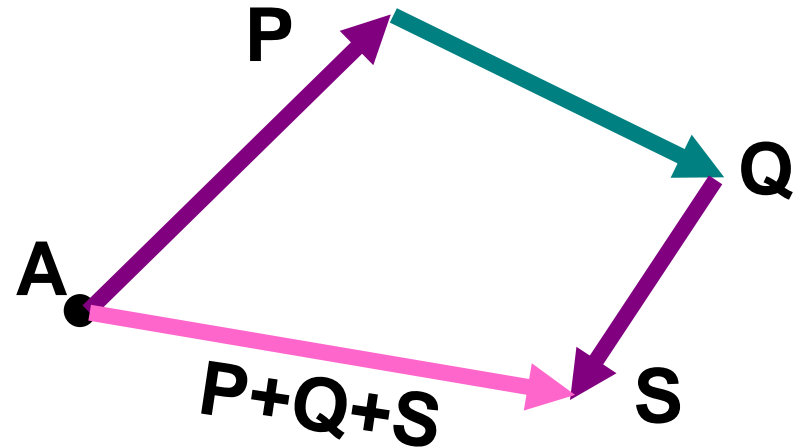


$$\mathbf{P} + \mathbf{Q} + \mathbf{S} = (\mathbf{P} + \mathbf{Q}) + \mathbf{S} = \mathbf{P} + (\mathbf{Q} + \mathbf{S})$$

Resultant of several concurrent forces

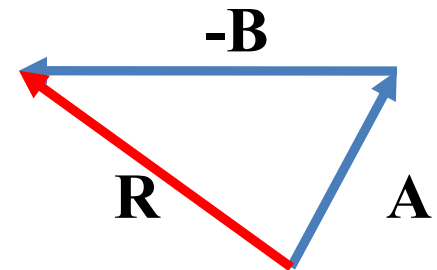
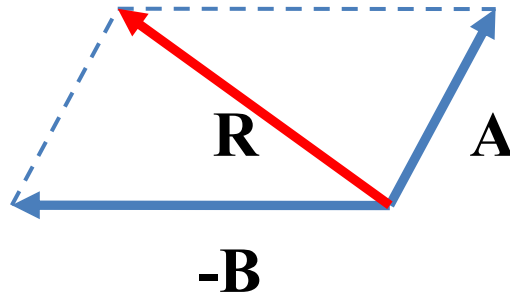
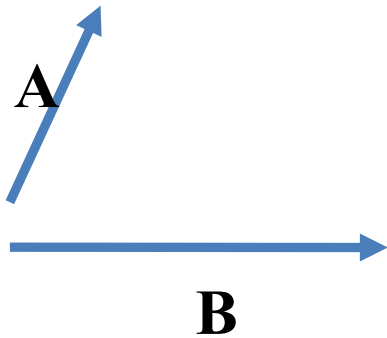


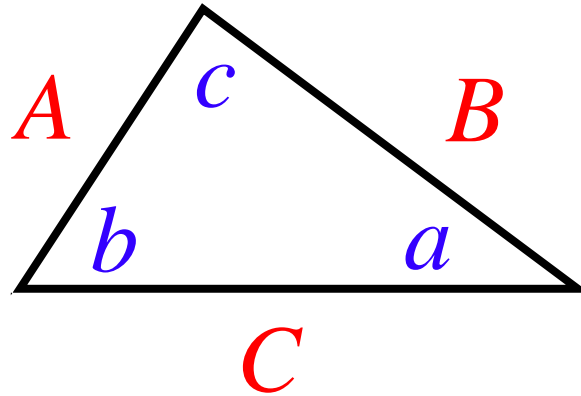
Using polygon rule



Force Subtraction

$$R = A - B = A + (-B)$$





law of sines

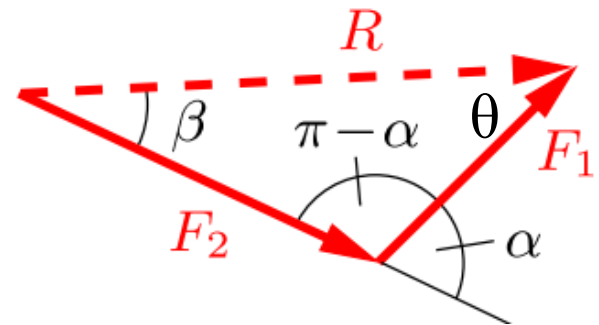
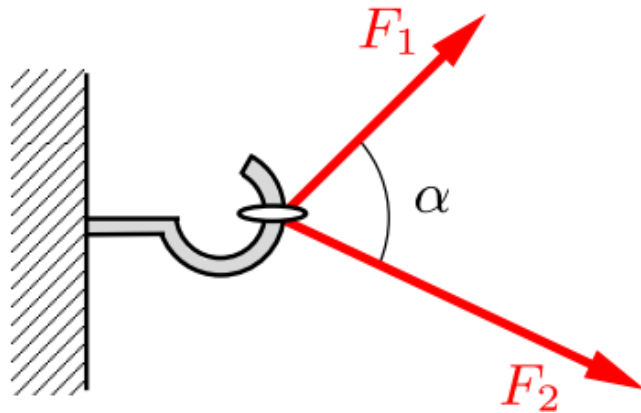
$$\frac{A}{\sin a} = \frac{B}{\sin b} = \frac{C}{\sin c}$$

law of cosines

$$C = \sqrt{A^2 + B^2 - 2AB \cos c}$$

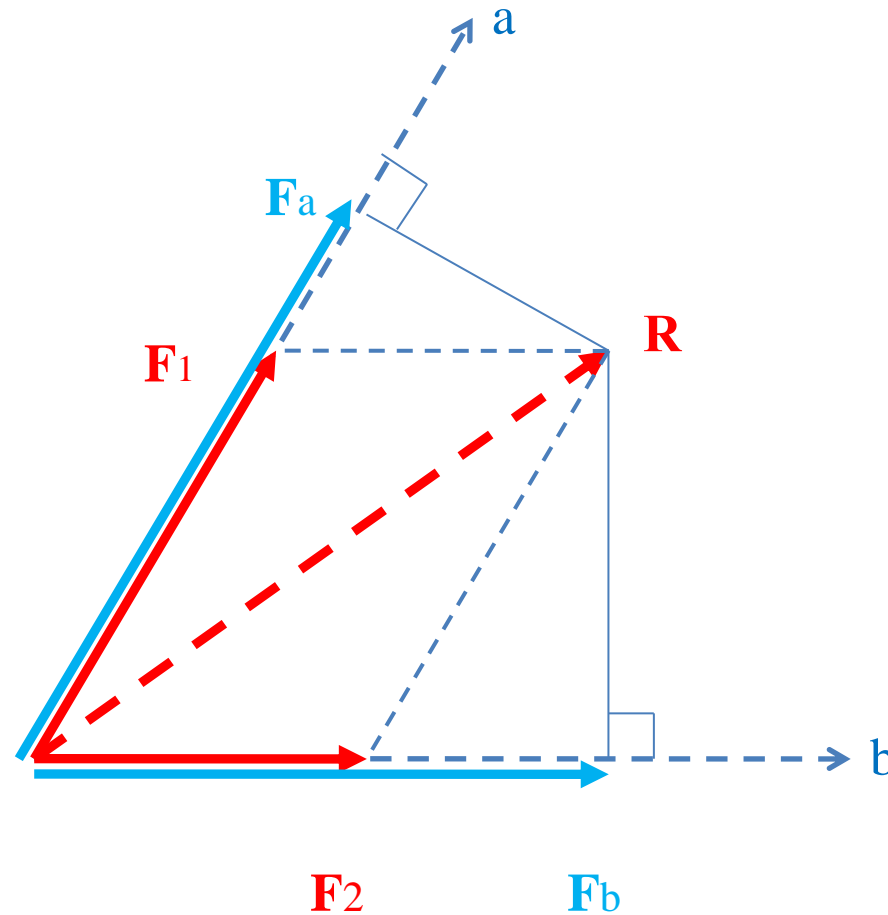
Example

- A hook carries two forces F_1 and F_2 , which define the angle α . Determine the magnitude and direction of the resultant.



$$R^2 = F_1^2 + F_2^2 - 2 F_1 F_2 \cos (\pi - \alpha) \quad \text{or} \quad \frac{R}{\sin (\pi - \alpha)} = \frac{F_1}{\sin \beta} = \frac{F_2}{\sin \theta}$$

Projection and Component

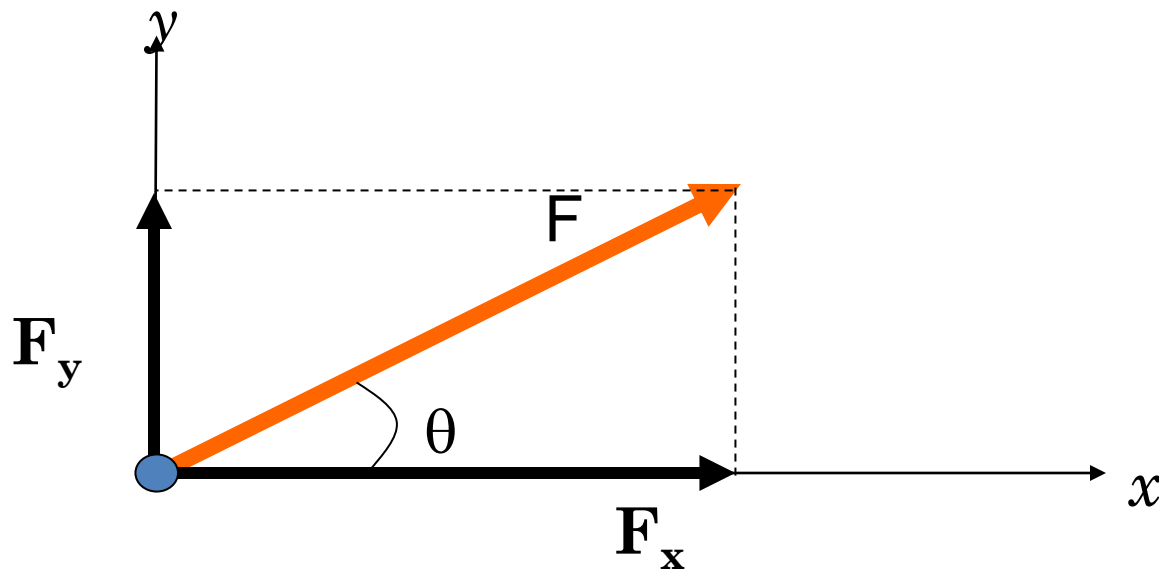


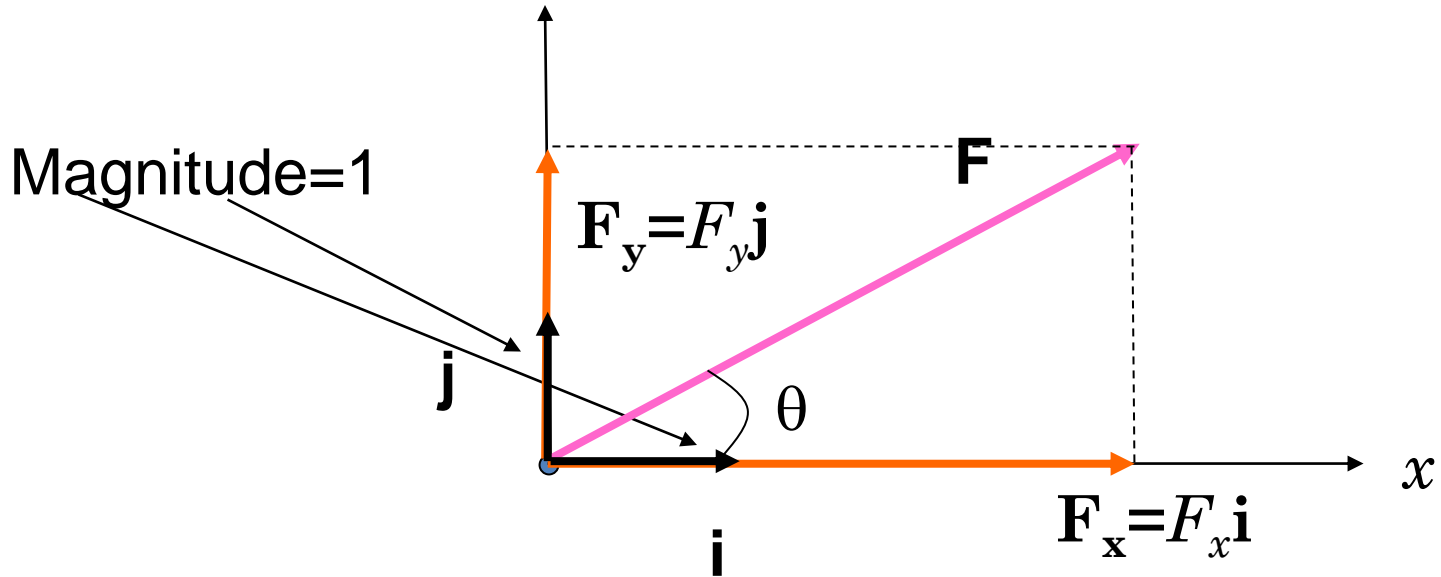
\mathbf{F}_a and \mathbf{F}_b are projections of \mathbf{R}

\mathbf{F}_1 and \mathbf{F}_2 components of \mathbf{R}

Rectangular Components

- The most common two-dimensional resolution of a force vector is into rectangular components.





- $\mathbf{F} = \mathbf{F}_x + \mathbf{F}_y$ where \mathbf{F}_x and \mathbf{F}_y are vector components of \mathbf{F} .
- $\mathbf{F} = F_x \mathbf{i} + F_y \mathbf{j}$ where F_x and F_y are the x and y scalar components of the vector \mathbf{F} . \mathbf{i} and \mathbf{j} are the **unit vectors** along the x and y axes,

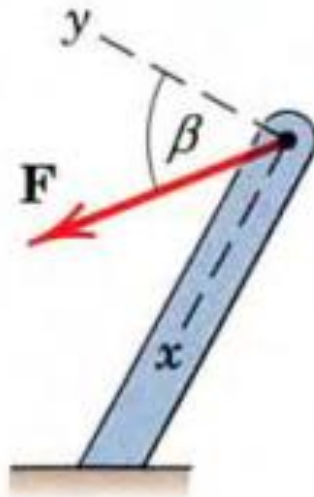
$$F_x = F \cos \theta$$

$$F_y = F \sin \theta$$

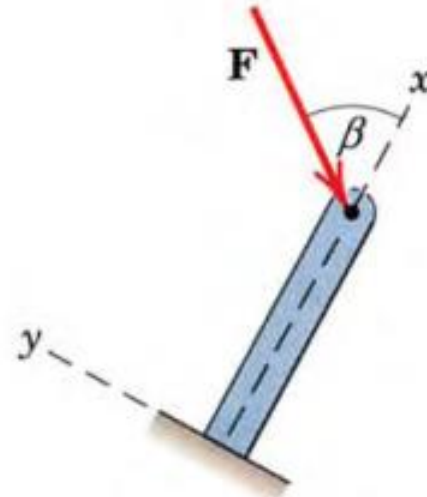
$$F = \sqrt{F_x^2 + F_y^2}$$

$$\tan \theta = \frac{F_y}{F_x}$$

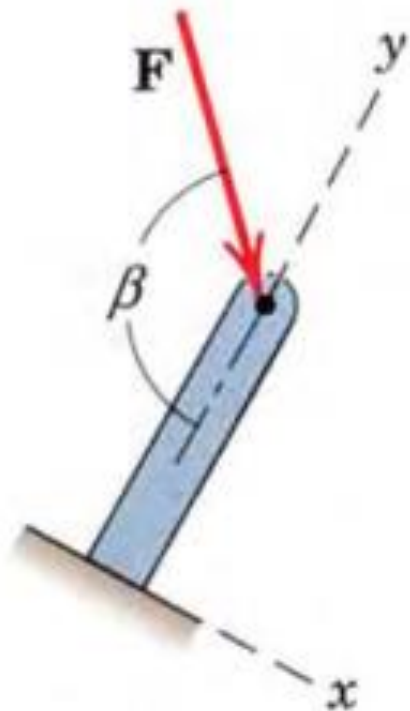
Rectangular Components of Forces



$$F_x = F \sin \beta$$
$$F_y = F \cos \beta$$

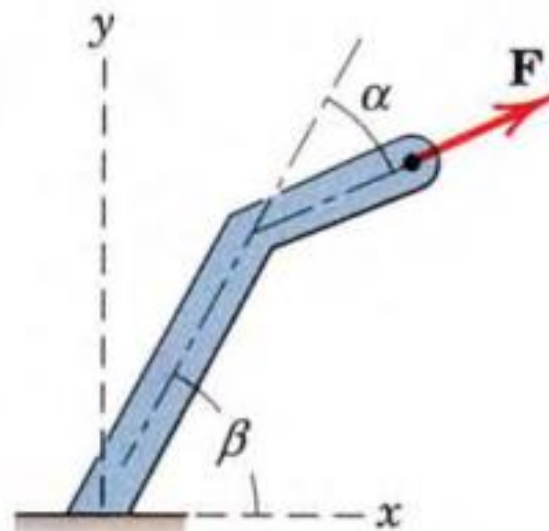


$$F_x = -F \cos \beta$$
$$F_y = -F \sin \beta$$



$$F_x = F \sin(\pi - \beta)$$

$$F_y = -F \cos(\pi - \beta)$$



$$F_x = F \cos(\beta - \alpha)$$

$$F_y = F \sin(\beta - \alpha)$$

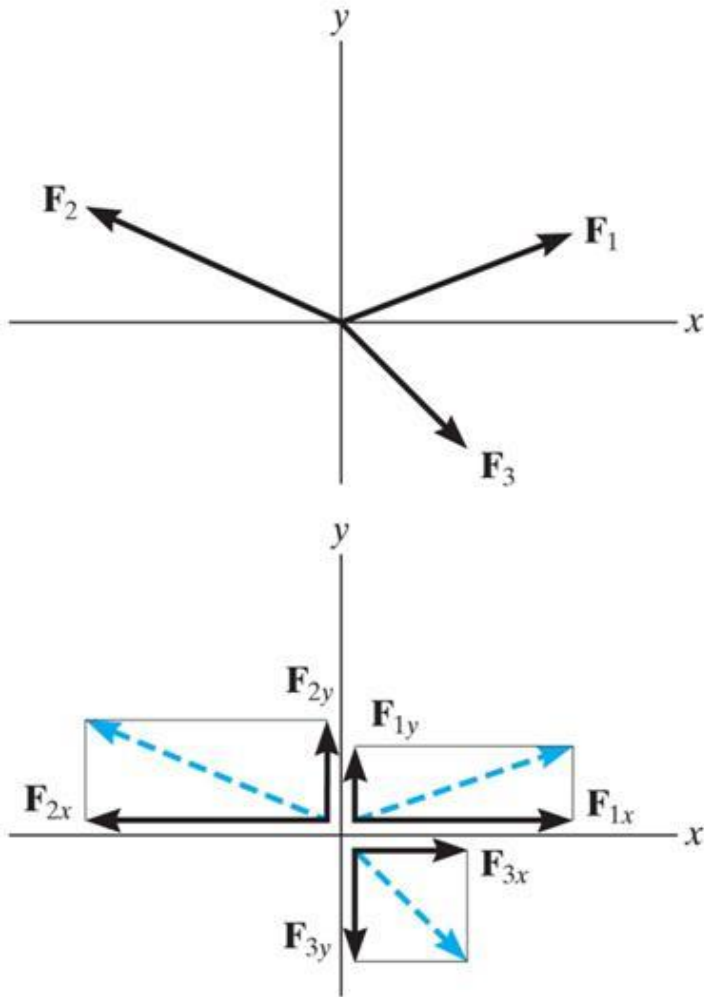
When **three or more coplanar forces** act on a particle, the rectangular components of their resultant **R** can be obtained by adding algebraically the corresponding components of the given forces.

$$R_x = \Sigma R_x \qquad R_y = \Sigma R_y$$

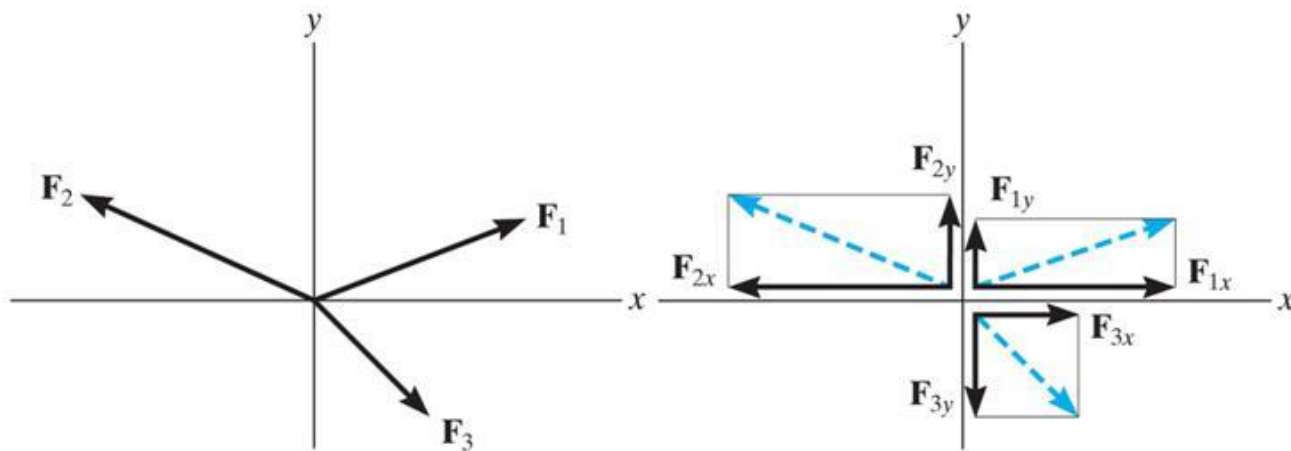
The magnitude and direction of **R** can be determined from

$$\tan \theta = \frac{R_y}{R_x} \qquad R = \sqrt{R_x^2 + R_y^2}$$

Addition of Several Vectors

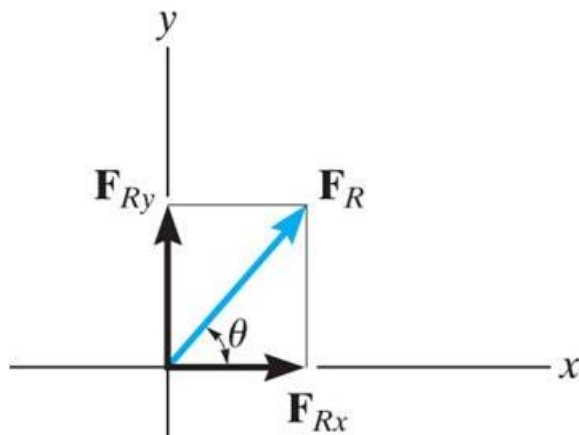


- Step 1 is to *resolve* each force into its *components*.
- Step 2 is to *add* all the *x-components* together, followed by adding all the *y-components* together. These two totals are the x and y components of the resultant vector.
- Step 3 is to *find* the *magnitude* and *angle* of the *resultant vector*.



- Break the three vectors into components, then add them.

$$\begin{aligned}
 \mathbf{F}_R &= \mathbf{F}_1 + \mathbf{F}_2 + \mathbf{F}_3 \\
 &= F_{1x}\mathbf{i} + F_{1y}\mathbf{j} - F_{2x}\mathbf{i} + F_{2y}\mathbf{j} + F_{3x}\mathbf{i} - F_{3y}\mathbf{j} \\
 &= (F_{1x} - F_{2x} + F_{3x})\mathbf{i} + (F_{1y} + F_{2y} - F_{3y})\mathbf{j} \\
 &= (F_{Rx})\mathbf{i} + (F_{Ry})\mathbf{j}
 \end{aligned}$$



$$\theta = \tan^{-1} \left| \frac{F_{Ry}}{F_{Rx}} \right|$$

$$F_R = \sqrt{F_{Rx}^2 + F_{Ry}^2}$$

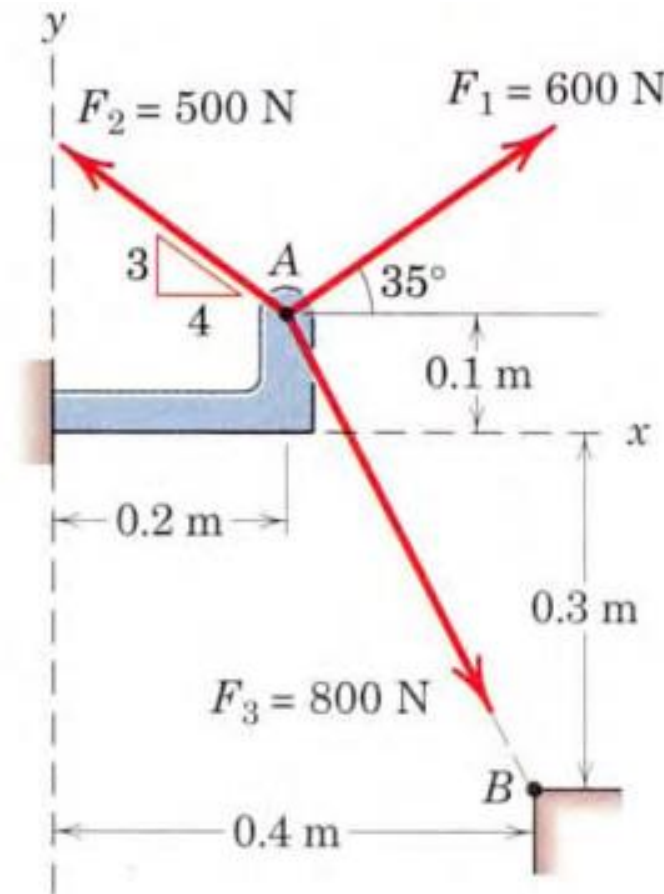
Examples

FORCES SYSTEMS

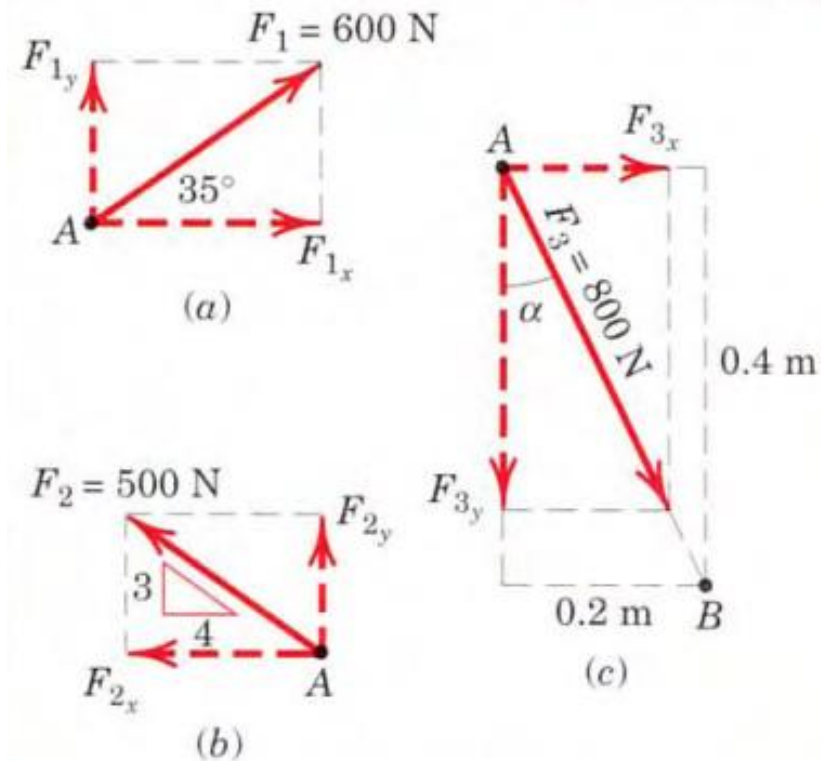
Example 1

- The forces \mathbf{F}_1 , \mathbf{F}_2 , and \mathbf{F}_3 all of which act on point A of the bracket, are specified in three different ways. Determine the x and y scalar components of each of the forces.

- $\mathbf{F}_{1x}=491\text{ N}$ $\mathbf{F}_{1y}=344\text{ N}$
- $\mathbf{F}_{2x}=-400\text{ N}$ $\mathbf{F}_{2y}=300\text{ N}$
- $\mathbf{F}_{3x}=358\text{ N}$ $\mathbf{F}_{3y}=-716\text{ N}$



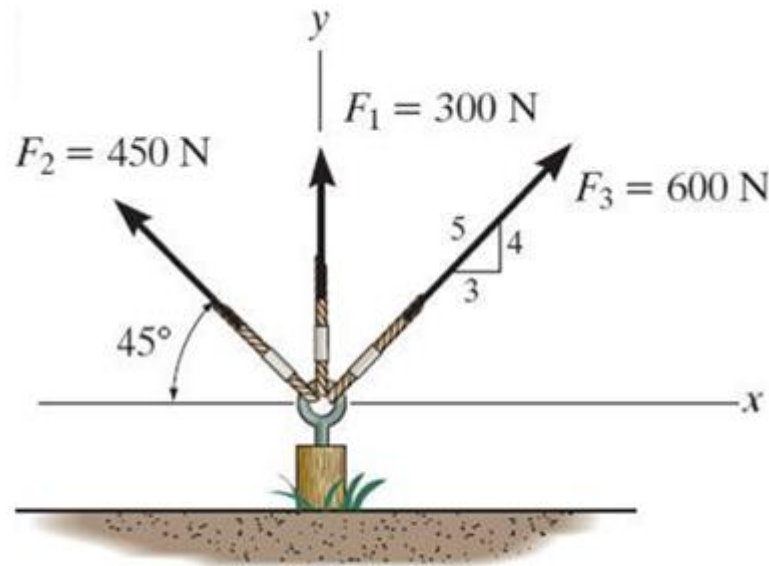
SOL. 1



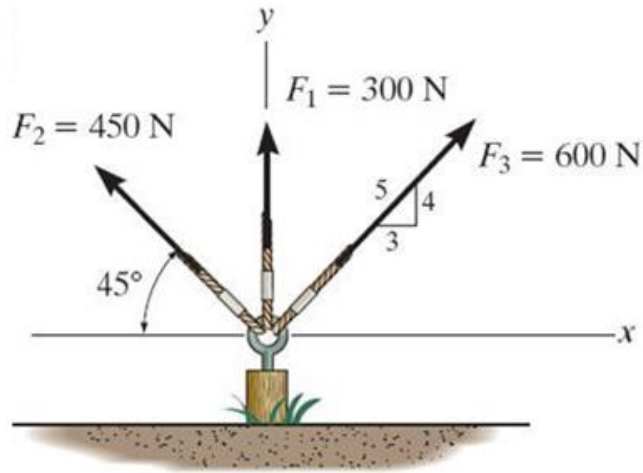
- $F_{1x} = 491 \text{ N}$ $F_{1y} = 344 \text{ N}$
- $F_{2x} = -400 \text{ N}$ $F_{2y} = 300 \text{ N}$
- $F_{3x} = 358 \text{ N}$ $F_{3y} = -716 \text{ N}$

Example 2

- Determine the Resultant Forces and angle of this forces.



SOL. 2



$$\mathbf{F}_1 = \{0 \mathbf{i} + 300 \mathbf{j}\} \text{ N}$$

$$\begin{aligned} \mathbf{F}_2 &= \{-450 \cos(45^\circ) \mathbf{i} + 450 \sin(45^\circ) \mathbf{j}\} \text{ N} \\ &= \{-318.2 \mathbf{i} + 318.2 \mathbf{j}\} \text{ N} \end{aligned}$$

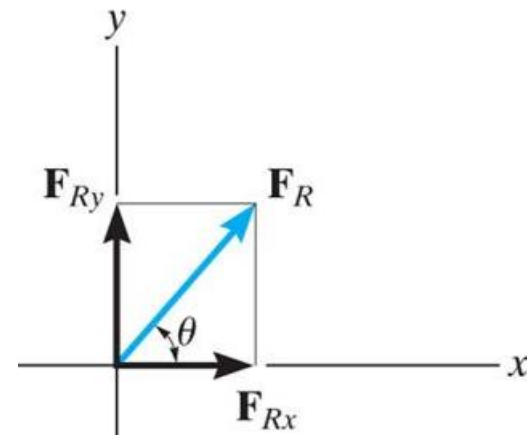
$$\begin{aligned} \mathbf{F}_3 &= \left\{ \left(\frac{3}{5}\right) 600 \mathbf{i} + \left(\frac{4}{5}\right) 600 \mathbf{j} \right\} \text{ N} \\ &= \{360 \mathbf{i} + 480 \mathbf{j}\} \text{ N} \end{aligned}$$

Summing up all the \mathbf{i} and \mathbf{j} components respectively, we get:

$$\begin{aligned} \mathbf{F}_R &= \{ (0 - 318.2 + 360) \mathbf{i} + (300 + 318.2 + 480) \mathbf{j} \} \text{ N} \\ &= \underline{\{41.80 \mathbf{i} + 1098 \mathbf{j}\} \text{ N}} \end{aligned}$$

$$F_R = ((41.80)^2 + (1098)^2)^{1/2} = \underline{1099 \text{ N}}$$

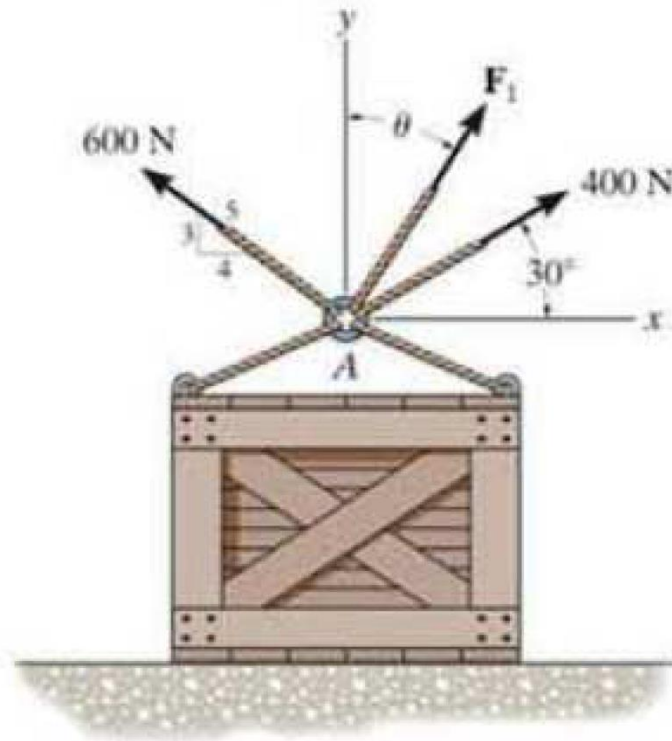
$$\phi = \tan^{-1}(1098/41.80) = \underline{87.8^\circ}$$



Example 3

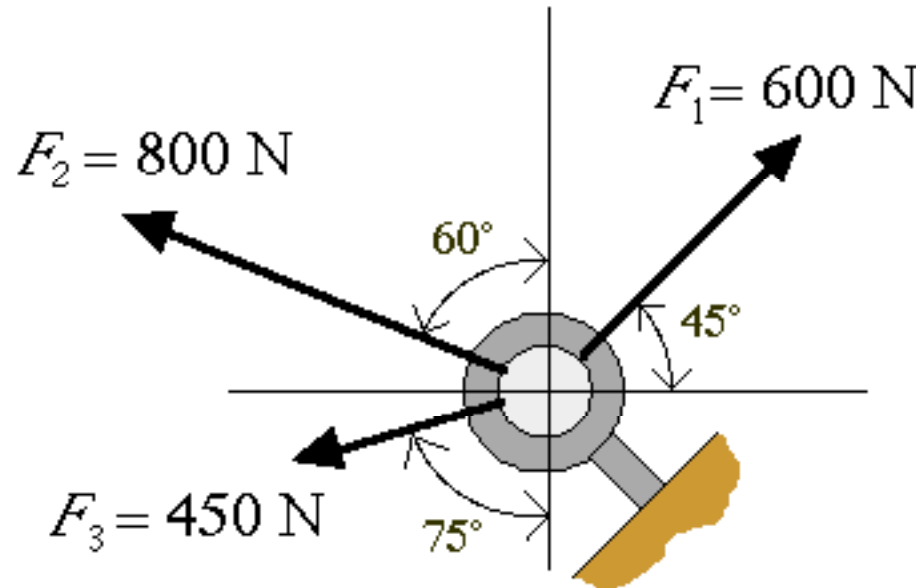
To have resultant Force in y direction with a magnitude of 800 N. Find the magnitude of F_1 and value of angle θ .

- Answer: $F_1=275$, $\theta=29,1^\circ$



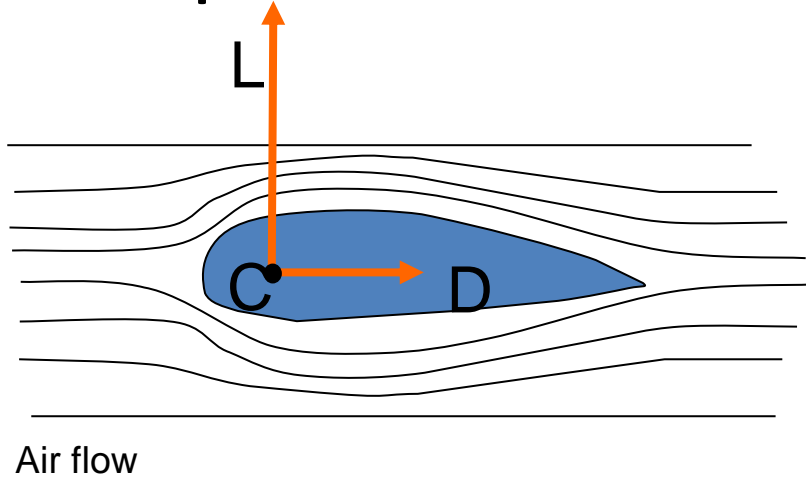
Example 4

A ring supports three forces. What is the resultant force applied to the ring?



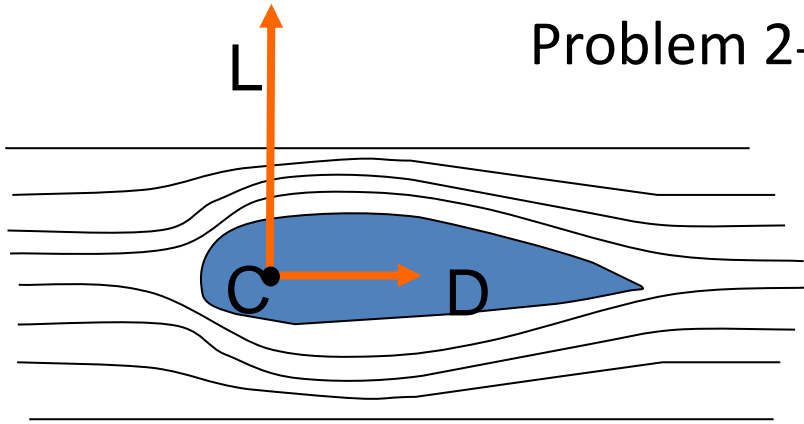
A: $\mathbf{R} = 998\text{ N @ } 134.9^\circ$

Example 5

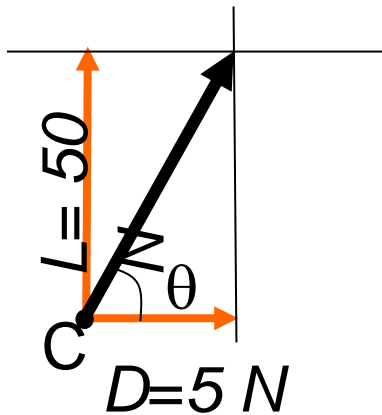


The ratio of the lift force **L** to the drag force **D** for the simple airfoil is $\mathbf{L/D} = 10$. If the lift force on a short section of the airfoil is 50 N , compute the magnitude of the resultant force **R** and the angle θ which it makes with the horizontal.

Problem 2-(Meriam and Kraige)



Air flow



$$\tan \theta = 50/5$$

$$\theta = \tan^{-1} 10$$
$$= 84.3^\circ$$

$$F = (50^2 + 5^2)^{0.50} =$$
$$50.2 \text{ N}$$