# ME 209 Numerical Methods

6. Interpolation Methods 1

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#### • Motivation:

- Often we have discrete data (tabulated, from experiments, etc) that we need to interpolate.
- Interpolating functions form the basis for numerical integration and differentiation techniques
  - Used for solving ODEs & PDEs
  - we will cover this later

### Concept:

- Choose a polynomial function to fit to the data (connect the dots)
- Solve for the coefficients of the polynomial
- Evaluate the polynomial wherever you want (interpolation)

T	ρ	λ	μ
K	kg/m³	W/(m K)	N s/m <sup>2</sup>
100	3.5562	0.0093	7.110e-06
150	2.3364	0.0138	1.034e-05
200	1.7458	0.0181	1.325e-05
250	1.3947	0.0223	1.596e-05
300	1.1614	0.0263	1.846e-05
350	0.9950	0.0300	2.082e-05
400	0.8711	0.0338	2.301e-05
450	0.7750	0.0373	2.507e-05
500	0.6864	0.0407	2.701e-05
550	0.6329	0.0439	2.884e-05
600	0.5804	0.0469	3.058e-05
650	0.5356	0.0497	3.225e-05
700	0.4975	0.0524	3.388e-05
750	0.4643	0.0549	3.546e-05
800	0.4354	0.0573	3.698e-05
850	0.4097	0.0596	3.843e-05
900	0.3868	0.0620	3.981e-05
950	0.3666	0.0643	4.113e-05
1000	0.3482	0.0667	4.244e-05

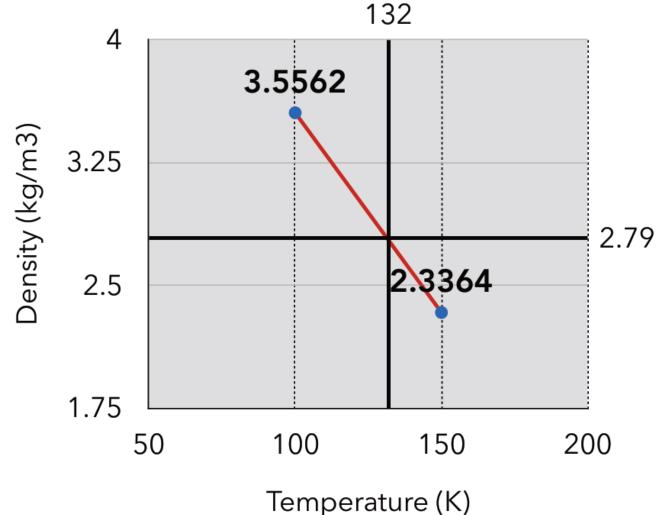
Incropera & DeWitt, Fundamentals of Heat and Mass Transfer, 4th ed.

# 132 4 3.5562 Density (kg/m3) 3.25 2.3364 2.5 1.75 50 100 150 200 Temperature (K)

#### Properties of air at atmospheric pressure

find density @ T = 132 K

#### Properties of air at atmospheric pressure



2.79 find density @ T = 132 K

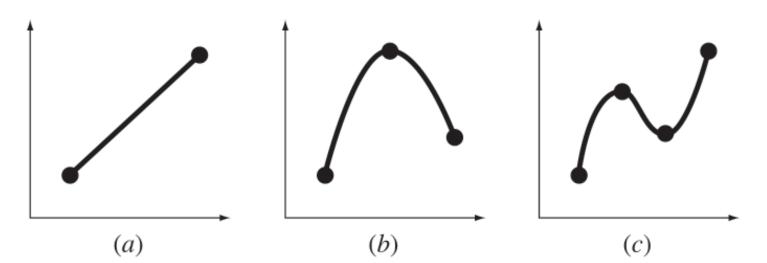
Find slope: 
$$s = \frac{2.34 - 3.56}{50} = -0.024$$

Find value:

$$\rho(132) = 3.56 + s \times (132 - 100) = 2.79$$

#### INTRODUCTION

- *Interpolation* is a method of estimating the intermediate values between precise data points. The most common method used for this purpose is polynomial interpolation.
- The basis of all interpolation algorithms is the fitting of some type of curve or function to a subset of the tabular data.
- Thus, we first fit a function that exactly passes through the given data points and than evaluate intermediate values using this function.



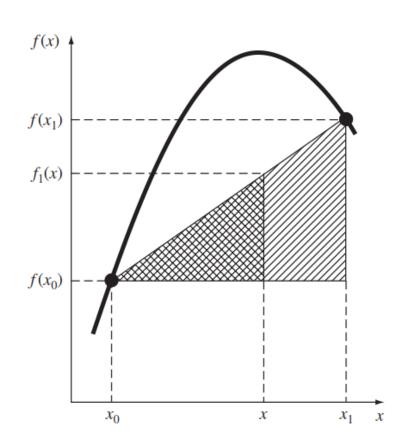
- a) first-order (linear) connecting two points,
- b) second-order (quadratic or parabolic) connecting three points, and
- c) third-order (cubic) connecting four points.

# NEWTON'S DIVIDED-DIFFERENCE INTERPOLATING POLYNOMIALS

There are a variety of alternative forms for expressing an interpolating polynomial. Newton's divided-difference interpolating polynomial is among the most popular and useful forms. Before presenting the general equation, we will introduce the first- and second-order versions

# **Linear Interpolation**

The simplest form of interpolation is to connect two data points with a straight line. This technique, called *linear interpolation*,



From similar triangles,

$$\frac{f_1(x) - f(x_0)}{x - x_0} = \frac{f(x_1) - f(x_0)}{x_1 - x_0}$$

linearformula

interpolation formula 
$$f_1(x) = f(x_0) + \frac{f(x_1) - f(x_0)}{x_1 - x_0} (x - x_0)$$

The slope of the line connecting the points, the term  $[f(x_1) - f(x_0)]/(x_1 - x_0)$  is a finite-divided-difference approximation of the first derivative

### **Linear Interpolation**

Problem Statement. Estimate the natural logarithm of 2 using linear interpolation. First, perform the computation by interpolating between  $\ln 1 = 0$  and  $\ln 6 = 1.791759$ . Then, repeat the procedure, but use a smaller interval from  $\ln 1$  to  $\ln 4$  (1.386294). Note that the true value of  $\ln 2$  is 0.6931472.

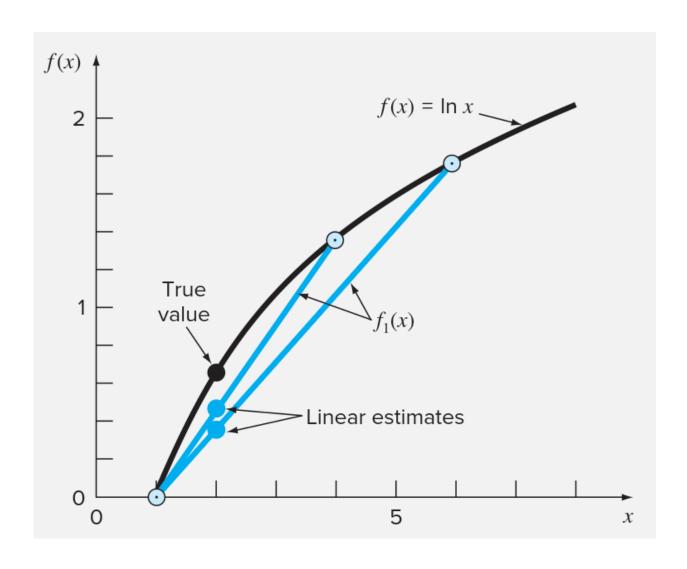
Solution. We use Eq. (18.2) and a linear interpolation for  $\ln 2$  from  $x_0 = 1$  to  $x_1 = 6$  to give

$$f_1(2) = 0 + \frac{1.791759 - 0}{6 - 1}(2 - 1) = 0.3583519$$

which represents an error of  $\varepsilon_t = 48.3\%$ . Using the smaller interval from  $x_0 = 1$  to  $x_1 = 4$  yields

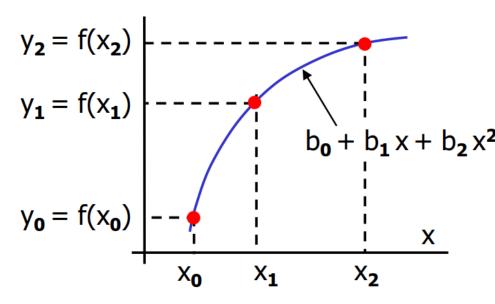
$$f_1(2) = 0 + \frac{1.386294 - 0}{4 - 1}(2 - 1) = 0.4620981$$

Thus, using the shorter interval reduces the percent relative error to  $\varepsilon_t = 33.3\%$ . Both



### **Quadratic Interpolation**

If three data points are available to find desired point, this can be accomplished with a second-order polynomial (also called a quadratic polynomial, or a parabola).



- Given:  $(x_0, y_0)$ ,  $(x_1, y_1)$  and  $(x_2, y_2)$
- A parabola passes from these three points.
- $b_0 + b_1 x + b_2 x^2$  Similar to the linear case, the equation of this parabola can be written as

$$f_2(x) = b_0 + b_1(x - x_0) + b_2(x - x_0)(x - x_1)$$

A simple procedure can be used to determine the values of the coefficients. For  $b^0$ , Eq. (18.3) with  $x = x^0$  can be used to compute

### **Quadratic Interpolation**

$$f_2(x) = b_0 + b_1(x - x_0) + b_2(x - x_0)(x - x_1)$$

A simple procedure can be used to determine the values of the coefficients. For  $b_0$ ,  $x = x^0$  can be used to compute

$$b_0 = f(x_0)$$
at  $x = x_1$ 

$$b_1 = \frac{f(x_1) - f(x_0)}{x_1 - x_0}$$

$$\frac{f(x_2) - f(x_1)}{x_2 - x_1} - \frac{f(x_1) - f(x_0)}{x_1 - x_0}$$
at  $x = x_2$ 

$$b_2 = \frac{x_1 - x_0}{x_2 - x_1}$$

#### **Quadratic Interpolation**

Problem Statement. Fit a second-order polynomial to the three points used in Example 18.1:

$$x_0 = 1$$
  $f(x_0) = 0$   
 $x_1 = 4$   $f(x_1) = 1.386294$   
 $x_2 = 6$   $f(x_2) = 1.791759$ 

Use the polynomial to evaluate ln 2.

Solution. Applying Eq. (18.4) yields

$$b_0 = 0$$

Equation (18.5) yields

$$b_1 = \frac{1.386294 - 0}{4 - 1} = 0.4620981$$

and Eq. (18.6) gives

$$b_2 = \frac{\frac{1.791759 - 1.386294}{6 - 4} - 0.4620981}{6 - 1} = -0.0518731$$

$$f_2(x) = 0 + 0.4620981(x - 1) - 0.0518731(x - 1)(x - 4)$$

which can be evaluated at x = 2 to give

$$f_2(2) = 0.5658444$$

which represents a relative error of  $\varepsilon_t = 18.4\%$ .

# **General Form of Newton's Interpolating Polynomials**

The preceding analysis can be generalized to fit an nth-order polynomial to n+1 data points. The nth-order polynomial is

$$f_n(x) = b_0 + b_1(x - x_0) + \dots + b_n(x - x_0)(x - x_1) \dots (x - x_{n-1})$$

$$b_0 = f(x_0)$$

$$b_1 = f[x_1, x_0]$$

$$b_2 = f[x_2, x_1, x_0]$$

•

•

•

$$b_n = f[x_n, x_{n-1}, \dots, x_1, x_0]$$

where the bracketed function evaluations are finite divided differences.

first finite divided difference

$$f[x_i, x_j] = \frac{f(x_i) - f(x_j)}{x_i - x_j}$$

second finite divided difference 
$$f[x_i, x_j, x_k] = \frac{f[x_i, x_j] - f[x_j, x_k]}{x_i - x_k}$$

nth finite divided difference

$$f[x_n, x_{n-1}, \dots, x_1, x_0] = \frac{f[x_n, x_{n-1}, \dots, x_1] - f[x_{n-1}, x_{n-2}, \dots, x_0]}{x_n - x_0}$$

These differences can be used to evaluate the coefficients b

Newton's divided-difference interpolating polynomial.

$$f_n(x) = f(x_0) + (x - x_0)f[x_1, x_0] + (x - x_0)(x - x_1)f[x_2, x_1, x_0]$$
  
+ \cdots + (x - x\_0)(x - x\_1) \cdots (x - x\_{n-1})f[x\_n, x\_{n-1}, \ldots, x\_0]

Graphical depiction of the recursive nature of finite divided differences.

i	Xi	$f(x_i)$	First	Second	Third
0 1 2 3	<ul><li>X<sub>0</sub></li><li>X<sub>1</sub></li><li>X<sub>2</sub></li><li>X<sub>3</sub></li></ul>		$f[x_1, x_0]$ $f[x_2, x_1]$ $f[x_3, x_2]$	$f[x_2, x_1, x_0]$ $f[x_3, x_2, x_1]$	$[x_3, x_2, x_1, x_0]$

Problem Statement.

data points at  $x_0 = 1$ ,  $x_1 = 4$ , and  $x_2 = 6$  were

used to estimate  $\ln 2$  with a parabola. Now, adding a fourth point,  $[x_3 = 5; f(x_3) = 1.609438]$ , estimate ln 2 with a third-order Newton's interpolating polynomial.

Solution. The third-order polynomial, with n = 3, is

$$f_3(x) = b_0 + b_1(x - x_0) + b_2(x - x_0)(x - x_1) + b_3(x - x_0)(x - x_1)(x - x_2)$$

The first finite divided differences for the problem are

$$f[x_1, x_0] = \frac{1.386294 - 0}{4 - 1} = 0.4620981$$

$$f[x_2, x_1] = \frac{1.791759 - 1.386294}{6 - 4} = 0.2027326$$

$$f[x_3, x_2] = \frac{1.609438 - 1.791759}{5 - 6} = 0.1823216$$

The second finite divided differences are

$$f[x_2, x_1, x_0] = \frac{0.2027326 - 0.4620981}{6 - 1} = -0.05187311$$
$$f[x_3, x_2, x_1] = \frac{0.1823216 - 0.2027326}{5 - 4} = -0.02041100$$

The third finite divided difference is m = 3

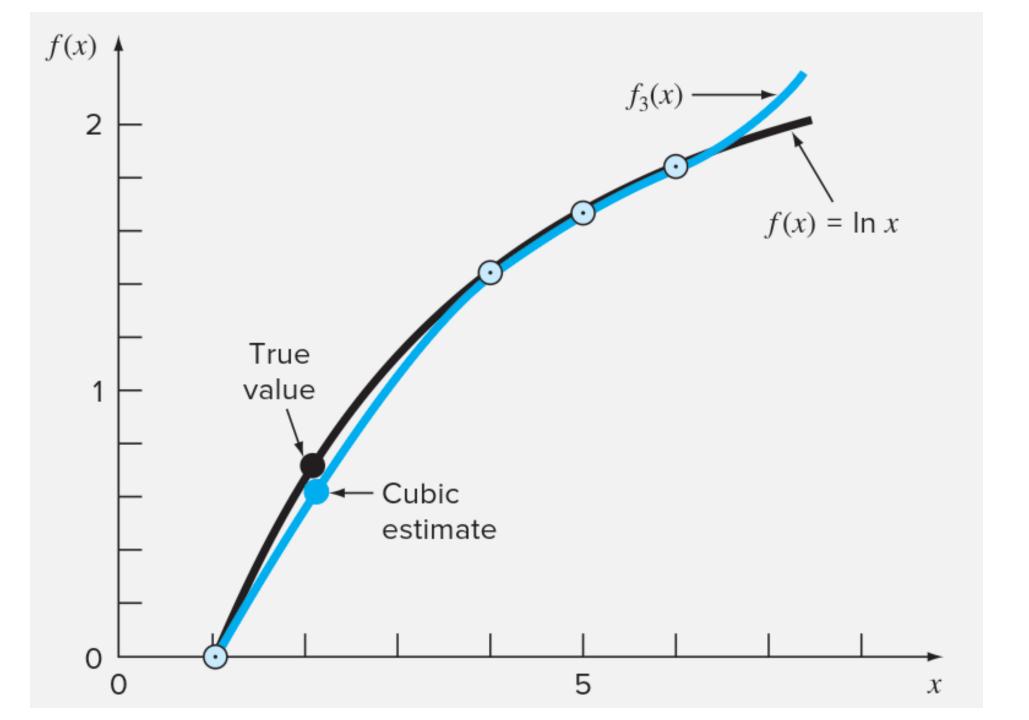
$$f[x_3, x_2, x_1, x_0] = \frac{-0.02041100 - (-0.05187311)}{5 - 1} = 0.007865529$$

The results for  $f[x_1, x_0]$ ,  $f[x_2, x_1, x_0]$ , and  $f[x_3, x_2, x_1, x_0]$  represent the coefficients  $b_1, b_2$ , and  $b_3$ , respectively

. With  $b_0 = f(x_0) = 0.0$ ,

$$f_3(x) = 0 + 0.4620981(x - 1) - 0.05187311(x - 1)(x - 4) + 0.007865529(x - 1)(x - 4)(x - 6)$$

which can be used to evaluate  $f_3(2) = 0.6287686$ , which represents a relative error of  $\varepsilon_t = 9.3\%$ .



The following logarithmic table is given.

X	f(x) = log(x)
4.0	0.60206
4.5	0.6532125
5.5	0.7403627
6.0	0.7781513

- (a) Interpolate log(5) using the points x=4 and x=6
- (b) Interpolate log(5) using the points x=4.5 and x=5.5Note that the exact value is log(5) = 0.69897

(a) Linear interpolation. 
$$f(x) = f(x_0) + (x - x_0) f[x_1, x_0]$$
  
 $x_0 = 4, x_1 = 6 \rightarrow f[x_1, x_0] = [f(6) - f(4)] / (6 - 4) = 0.0880046$   
 $f(5) \approx f(4) + (5 - 4) 0.0880046 = 0.690106$   $\epsilon_t = 1.27 \%$ 

(b) Again linear interpolation. But this time

$$x_0 = 4.5, x_1 = 5.5 \rightarrow f[x_1, x_0] = [f(5.5) - f(4.5)] / (5.5 - 4.5) = 0.0871502$$
  
 $f(5) \approx f(4.5) + (5 - 4.5) 0.0871502 = 0.696788$   $\epsilon_t = 0.3 \%$ 

- (c) Interpolate log(5) using the points x=4.5, x=5.5 and x=6
- (c) Quadratic interpolation.

$$x_0 = 4.5, x_1 = 5.5, x_2 = 6 \rightarrow f[x_1, x_0] = 0.0871502$$
 (already calculated)   
  $f[x_2, x_1] = [f(6) - f(5.5)] / (6 - 5.5) = 0.0755772$    
  $f[x_2, x_1, x_0] = \{f[x_2, x_1] - f[x_1, x_0]\} / (6 - 4.5) = -0.0077153$    
  $f(5) \approx 0.696788 + (5 - 4.5)(5 - 5.5) (-0.0077153) = 0.698717$   $\epsilon_t = 0.04 \%$ 

- Note that 0.696788 was calculate in part (b).
- Errors decrease when the points used are closer to the interpolated point.
- Errors decrease as the degree of the interpolating polynomial increases.

### **Finite Divided Difference (FDD) Table**

Finite divided differences used in the Newton's Interpolating Polynomials can be presented in a table form. This makes the calculations much simpler.

Х	f( )	f[,]	f[,,]	f[,,,]
x <sub>o</sub>	f(x <sub>0</sub> )	f [x <sub>1</sub> , x <sub>0</sub> ]	f [x <sub>2</sub> , x <sub>1</sub> , x <sub>0</sub> ]	f [x <sub>3</sub> , x <sub>2</sub> , x <sub>1</sub> , x <sub>0</sub> ]
<b>X</b> <sub>1</sub>	f(x <sub>1</sub> )	f [x <sub>2</sub> , x <sub>1</sub> ]	f [x <sub>3</sub> , x <sub>2</sub> , x <sub>1</sub> ]	
X <sub>2</sub>	f(x <sub>2</sub> )	f [x <sub>3</sub> , x <sub>2</sub> ]		
Х <sub>3</sub>	f(x <sub>3</sub> )			

Х	f( )	f[,]	f[,,]	f[,,,]
4	0.6020600	0.1023050	-0.0101032	0.001194
4.5	0.6532125	0.0871502	-0.0077153	
5.5	0.7403627	0.0755772		
6	0.7781513			

Use this previously calculated table to interpolate for log(5).

- (a) Using points x=4 and x=4.5.
- (b) Using points x=4.5 and x=5.5.
- (c) Using points x=4 and x=6.
- (d) Using points x=4.5, x=5.5 and x=6.
- (e) Using all four points.

(a) Using points x=4 and x=4.5.

log (5) 
$$\approx$$
 0.60206 + (5 - 4) 0.102305 = 0.704365  $\epsilon_t$  = 0.8 % (this is extrapolation)

(b) Using points x=4.5 and x=5.5.

$$\log (5) \approx 0.6532125 + (5 - 4.5) \ 0.0871502 = 0.696788$$
  $\varepsilon_t = 0.3 \%$ 

(c) Using points x=4 and x=6.

The entries of the above table can not be used for this interpolation.

(d) Using points x=4.5, x=5.5 and x=6.

$$\log (5) \approx 0.6532125 + (5-4.5) \ 0.0871502 + (5-4.5)(5-5.5)(-0.0077153) = 0.698717$$
  $\epsilon_{\mathbf{t}} = 0.04 \ \%$ 

(e) Using all four points.

$$\log (5) \approx 0.60206 + (5 - 4) \ 0.102305 + (5 - 4)(5 - 4.5)(-0.0101032) \\ + (5 - 4)(5 - 4.5)(5 - 5.5)(0.001194) = 0.6990149 \qquad \epsilon_{\mathbf{t}} = 0.006 \ \%$$

### **Errors of Newton's Interpolating Polynomials**

$$f_{n}(x) = f(x_{0}) + (x - x_{0}) f[x_{1}, x_{0}] + (x - x_{0})(x - x_{1}) f[x_{2}, x_{1}, x_{0}] + \dots$$

$$+ (x - x_{0})(x - x_{1}) \cdots (x - x_{n-1}) f[x_{n}, x_{n-1}, \dots, x_{1}, x_{0}]$$

- The structure of Newton's Interpolating Polynomials is similar to the Taylor series.
- Remainder (truncation error) for the Taylor series was  $R_n = \frac{f^{n+1}(\xi)}{(n+1)!}(x_{i+1} x_i)^{n+1}$
- Similarly the remainder for the n<sup>th</sup> order interpolating polynomial is

$$R_n = \frac{f^{n+1}(\xi)}{(n+1)!}(x-x_0)(x-x_1)\dots(x-x_n)$$

where  $\xi$  is somewhere in the interval containing the interpolated point x and other data points.

- But usually only the set of data points is given and the function f is not known.
- An alternative formulation uses a finite divided difference to approximate the (n+1)<sup>th</sup> derivative.

$$R_n \approx f[x, x_n, x_{n-1}, ..., x_0](x - x_0)(x - x_1)...(x - x_n)$$

- But this includes f(x) which is not known.
- Error can be predicted if an additional data point  $(x_{n+1})$  is availbale

$$R_n \approx f[x_{n+1}, x_n, x_{n-1}, ..., x_0](x-x_0)(x-x_1)...(x-x_n)$$

which is nothing but  $f_{n+1}(x) - f_n(x)$ 

#### LAGRANGE INTERPOLATING POLYNOMIALS

The Lagrange interpolating polynomial is simply a reformulation of the Newton polynomial that avoids the computation of divided differences. It can be represented concisely as

$$f_n(x) = \sum_{i=0}^n L_i(x) f(x_i)$$

where Langrange function is:

$$L_i(x) = \prod_{\substack{j=0\\j\neq i}}^n \frac{x - x_j}{x_i - x_j}$$

and Π designates the "product of."

For example, the linear version (n = 1) is

$$f_1(x) = \frac{x - x_1}{x_0 - x_1} f(x_0) + \frac{x - x_0}{x_1 - x_0} f(x_1)$$

and the second-order version is

$$f_2(x) = \frac{(x - x_1)(x - x_2)}{(x_0 - x_1)(x_0 - x_2)} f(x_0) + \frac{(x - x_0)(x - x_2)}{(x_1 - x_0)(x_1 - x_2)} f(x_1)$$
$$+ \frac{(x - x_0)(x - x_1)}{(x_2 - x_0)(x_2 - x_1)} f(x_2)$$

Problem Statement. Use a Lagrange interpolating polynomial of the first and second order to evaluate ln 2 on the basis of the data given in Example 18.2:

$$x_0 = 1$$
  $f(x_0) = 0$   
 $x_1 = 4$   $f(x_1) = 1.386294$   
 $x_2 = 6$   $f(x_2) = 1.791760$ 

Solution. The first-order polynomial [Eq. (18.22)] can be used to obtain the estimate at x = 2,

$$f_1(2) = \frac{2-4}{1-4}0 + \frac{2-1}{4-1}1.386294 = 0.4620981$$

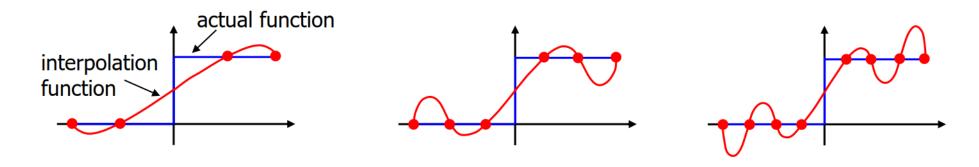
In a similar fashion, the second-order polynomial is developed as [Eq. (18.23)]

$$f_2(2) = \frac{(2-4)(2-6)}{(1-4)(1-6)}0 + \frac{(2-1)(2-6)}{(4-1)(4-6)}1.386294$$
$$+ \frac{(2-1)(2-4)}{(6-1)(6-4)}1.791760 = 0.5658444$$

As expected, both these results agree with those previously obtained using Newton's interpolating polynomial.

### **SPLINE INTERPOLATION**

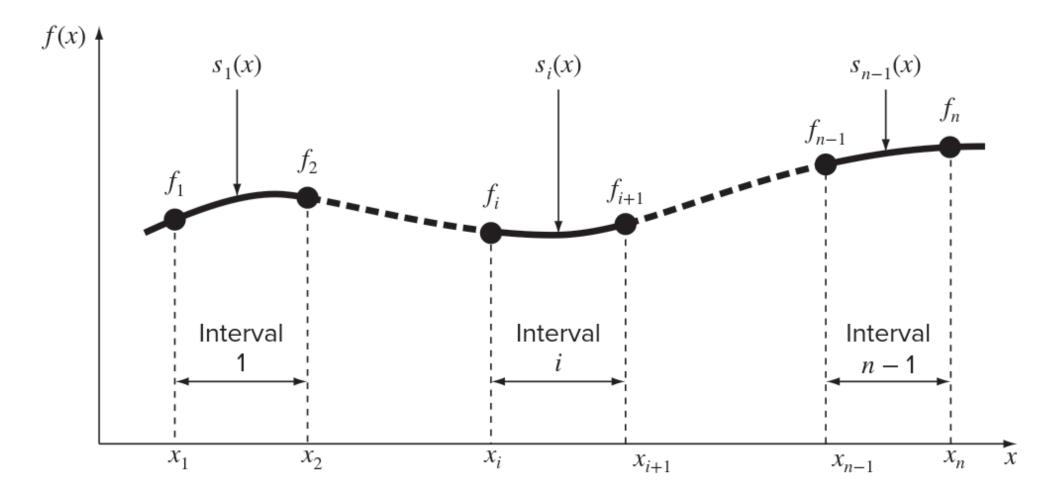
- We learned how to interpolate between n+1 data points using n<sup>th</sup> order polynomials.
- For high number of data points (typically n > 6 or 7), high order polynomials are necessary, but sometimes they suffer from oscillatory behavior.



- Instead of using a single high order polynomial that passes through all data points, we can use different lower order polynomials between each data pair.
- These lower order polynomials that pass through only two points are called splines.
- Third order (cubic) splines are the most preferred ones.



# **Linear Splines**



The notation used for splines

# **Linear Splines**

- For n data points (i = 1, 2, ..., n), there are n 1 intervals. Each interval i has its own spline function,  $s_i(x)$ .
- For linear splines, each function is merely the straight line connecting the two points at each end of the interval, which is formulated as

$$s_i(x) = a_i + b_i(x - x_i)$$

where  $a_i$  is the intercept, which is defined as  $a_i = f_i = f(x_i)$ 

and  $b_i$  is the slope of the straight line connecting the points

$$b_i = \frac{f_{i+1} - f_i}{x_{i+1} - x_i}$$

$$s_i(x) = f_i + \frac{f_{i+1} - f_i}{x_{i+1} - x_i} (x - x_i)$$

These equations can be used to evaluate the function at any point between  $x_1$  and  $x_n$  by first locating the interval within which the point lies.

Problem Statement. Fit the data in Table 18.1 with first-order splines. Evaluate the function at x = 5.

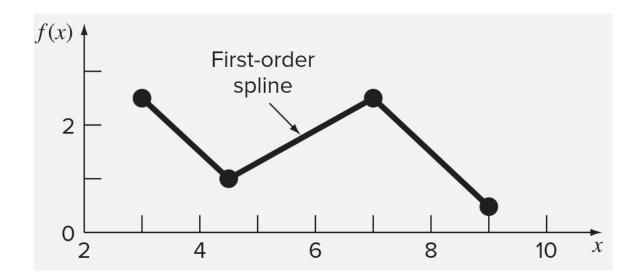
<b>TABLE 18.1</b>	Data to be fit with spline functions.	
i	<b>X</b> <sub>i</sub>	f <sub>i</sub>
1	3.0	2.5
2	4.5	1.0
3	7.0	2.5
4	9.0	0.5

#### Solution.

For example, for the second interval from x = 4.5 to x = 7, the function is

$$s_2(x) = 1.0 + \frac{2.5 - 1.0}{7.0 - 4.5}(x - 4.5)$$

$$s_2(x) = 1.0 + \frac{2.5 - 1.0}{7.0 - 4.5}(5 - 4.5) = 1.3$$



# **Quadratic Splines**

- To ensure that the nth derivatives are continuous at the knots, a spline of at least n+1 order must be used.
- Third-order polynomials or cubic splines that ensure continuous first and second derivatives are most frequently used in practice.
- The objective in quadratic splines is to derive a second-order polynomial for each interval between data points.

$$s_i(x) = a_i + b_i(x - x_i) + c_i(x - x_i)^2$$

For n data points (i = 1, 2, ..., n), there are n - 1 intervals and, consequently, 3(n - 1) unknown constants (the a's, b's, and c's) to evaluate. Therefore, 3(n - 1) equations or conditions are required to evaluate the unknowns.

**1.** The function must pass through all the points. This is called a *continuity condition*. It can be expressed mathematically as

$$f_i = a_i + b_i(x_i - x_i) + c_i(x_i - x_i)^2$$

which simplifies to

$$a_i = f_i \tag{18.32}$$

$$s_i(x) = f_i + b_i(x - x_i) + c_i(x - x_i)^2$$

2. The function values of adjacent polynomials must be equal at the knots.

$$f_i + b_i h_i + c_i h_i^2 = f_{i+1}$$
  $h_i = x_{i+1} - x_i$ 

**3.** The first derivatives at the interior nodes must be equal.

$$s_i'(x) = b_i + 2c_i(x - x_i)$$
  $b_i + 2c_ih_i = b_{i+1}$ 

**4.** Assume that the second derivative is zero at the first point.  $c_1 = 0$ 

Problem Statement. Fit quadratic splines to the same data employed in previous example (Table 18.1). Use the results to estimate the value of the function at x = 5.

<b>TABLE 18.1</b>	Data to be fit with splin	e functions.
i	<b>X</b> <sub>i</sub>	f <sub>i</sub>
1	3.0	2.5
2	4.5	1.0
3	7.0	2.5
4	9.0	0.5

Solution. For the present problem, we have four data points and n = 3 intervals. Therefore, after applying the continuity condition and the zero second-derivative condition, this means that 2(4 - 1) - 1 = 5 conditions are required. Equation (18.34) is written for i = 1 through 3 (with  $c_1 = 0$ ) to give

$$f_1 + b_1 h_1 = f_2$$

$$f_2 + b_2 h_2 + c_2 h_2^2 = f_3$$

$$f_3 + b_3 h_3 + c_3 h_3^2 = f_4$$

Continuity of derivatives, Eq. (18.35), creates an additional 3 - 1 = 2 conditions (again, recall that  $c_1 = 0$ ):

$$b_1 = b_2 b_2 + 2c_2h_2 = b_3$$

The necessary function and interval width values are

$$f_1 = 2.5$$
  $h_1 = 4.5 - 3.0 = 1.5$   
 $f_2 = 1.0$   $h_2 = 7.0 - 4.5 = 2.5$   
 $f_3 = 2.5$   $h_3 = 9.0 - 7.0 = 2.0$   
 $f_4 = 0.5$ 

These values can be substituted into the conditions, which can be expressed in matrix form as

$$\begin{bmatrix} 1.5 & 0 & 0 & 0 & 0 \\ 0 & 2.5 & 6.25 & 0 & 0 \\ 0 & 0 & 0 & 2 & 4 \\ 1 & -1 & 0 & 0 & 0 \\ 0 & 1 & 5 & -1 & 0 \end{bmatrix} \begin{pmatrix} b_1 \\ b_2 \\ c_2 \\ b_3 \\ c_3 \end{pmatrix} = \begin{pmatrix} -1.5 \\ 1.5 \\ -2 \\ 0 \\ 0 \end{pmatrix}$$

These equations can be solved with the results:

$$b_1 = -1$$
  
 $b_2 = -1$   $c_2 = 0.64$   
 $b_3 = 2.2$   $c_3 = -1.6$ 

These results, along with the values for the a's [Eq. (18.32)], can be substituted into the original quadratic equations to develop the following quadratic splines for each interval:

$$s_1(x) = 2.5 - (x - 3)$$

$$s_2(x) = 1.0 - (x - 4.5) + 0.64(x - 4.5)^2$$

$$s_3(x) = 2.5 + 2.2(x - 7.0) - 1.6(x - 7.0)^2$$

Because x = 5 lies in the second interval, we use  $s_2$  to make the prediction,

$$s_2(5) = 1.0 - (5 - 4.5) + 0.64(5 - 4.5)^2 = 0.66$$

# **Cubic Splines**

- Cubic splines are most frequently used in practice.
- Cubic splines are preferred because they provide the simplest representation that exhibits the desired appearance of smoothness.
- The objective with cubic splines is to derive a third-order polynomial for each interval between knots as represented generally by

$$s_i(x) = a_i + b_i(x - x_i) + c_i(x - x_i)^2 + d_i(x - x_i)^3$$

Thus, for n data points (i = 1, 2, . . . , n), there are n - 1 intervals and 4(n - 1) unknown coefficients to evaluate.

Consequently, 4(n-1) conditions are required for their evaluation.

The final equations can now be written in matrix form as

$$\begin{bmatrix} 1 \\ h_1 & 2(h_1 + h_2) & h_2 \\ h_{n-2} & 2(h_{n-2} + h_{n-1}) & h_{n-1} \\ 1 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_{n-1} \\ c_n \end{bmatrix} = \begin{bmatrix} 0 \\ 3(f[x_3, x_2] - f[x_2, x_1]) \\ 3(f[x_n, x_{n-1}] - f[x_{n-1}, x_{n-2}]) \\ 0 \end{bmatrix}$$

$$h_{i} = x_{i+1} - x_{i}$$

$$a_{i} = f_{i}$$

$$b_{i} = \frac{f_{i+1} - f_{i}}{h_{i}} - \frac{h_{i}}{3}(2c_{i} + c_{i+1})$$

$$d_{i} = \frac{c_{i+1} - c_{i}}{3h_{i}}$$

Problem Statement. Fit cubic splines to the same data used in previous examples (Table 18.1). Utilize the results to estimate the value of the function at x = 5.

<b>TABLE 18.1</b>	Data to be fit with spline functions.	
i	<b>X</b> <sub>i</sub>	<b>f</b> <sub>i</sub>
1	3.0	2.5
2	4.5	1.0
3	7.0	2.5
4	9.0	0.5

Solution. The first step is to generate the set of simultaneous equations that will be utilized to determine the *c* coefficients:

$$\begin{bmatrix} 1 & & & & \\ h_1 & 2(h_1 + h_2) & h_2 & \\ & h_2 & 2(h_2 + h_3) & h_3 \\ & & 1 \end{bmatrix} \begin{cases} c_1 \\ c_2 \\ c_3 \\ c_4 \end{cases} = \begin{cases} 0 \\ 3(f[x_3, x_2] - f[x_2, x_1]) \\ 3(f[x_4, x_3] - f[x_3, x_2]) \\ 0 \end{cases}$$

The necessary function and interval width values are

$$f_1 = 2.5$$
  $h_1 = 4.5 - 3.0 = 1.5$   
 $f_2 = 1.0$   $h_2 = 7.0 - 4.5 = 2.5$   
 $f_3 = 2.5$   $h_3 = 9.0 - 7.0 = 2.0$   
 $f_4 = 0.5$ 

$$\begin{bmatrix} 1 \\ 1.5 & 8 & 2.5 \\ & 2.5 & 9 & 2 \\ & & 1 \end{bmatrix} \begin{Bmatrix} c_1 \\ c_2 \\ c_3 \\ c_4 \end{Bmatrix} = \begin{Bmatrix} 0 \\ 4.8 \\ -4.8 \\ 0 \end{Bmatrix}$$

$$c_1 = 0$$
  $c_2 = 0.839543726$   
 $c_3 = -0.766539924$   $c_4 = 0$ 

#### Compute the b's and d's:

$$b_1 = -1.419771863$$
  $d_1 = 0.186565272$   
 $b_2 = -0.160456274$   $d_2 = -0.214144487$   
 $b_3 = 0.022053232$   $d_3 = 0.127756654$ 

$$s_1(x) = 2.5 - 1.419771863(x - 3) + 0.186565272(x - 3)^3$$

$$s_2(x) = 1.0 - 0.160456274(x - 4.5) + 0.839543726(x - 4.5)^2$$

$$- 0.214144487(x - 4.5)^3$$

$$s_3(x) = 2.5 + 0.022053232(x - 7.0) - 0.766539924(x - 7.0)^2$$

$$+ 0.127756654(x - 7.0)^3$$

The three equations can then be employed to compute values within each interval. For example, the value at x = 5, which falls within the second interval, is calculated as

$$s_2(5) = 1.0 - 0.160456274(5 - 4.5) + 0.839543726(5 - 4.5)^2 - 0.214144487(5 - 4.5)^3$$
  
= 1.102889734.